

original with solution  
M.R. Asharif 2009/6/18

Digital Signal Processing

Undergraduate Course Student's Name:

Mid-Term Examination Student's No.

2009.6.19 [write your answer in the blocks, each one 10 score]

University of the Ryukyus

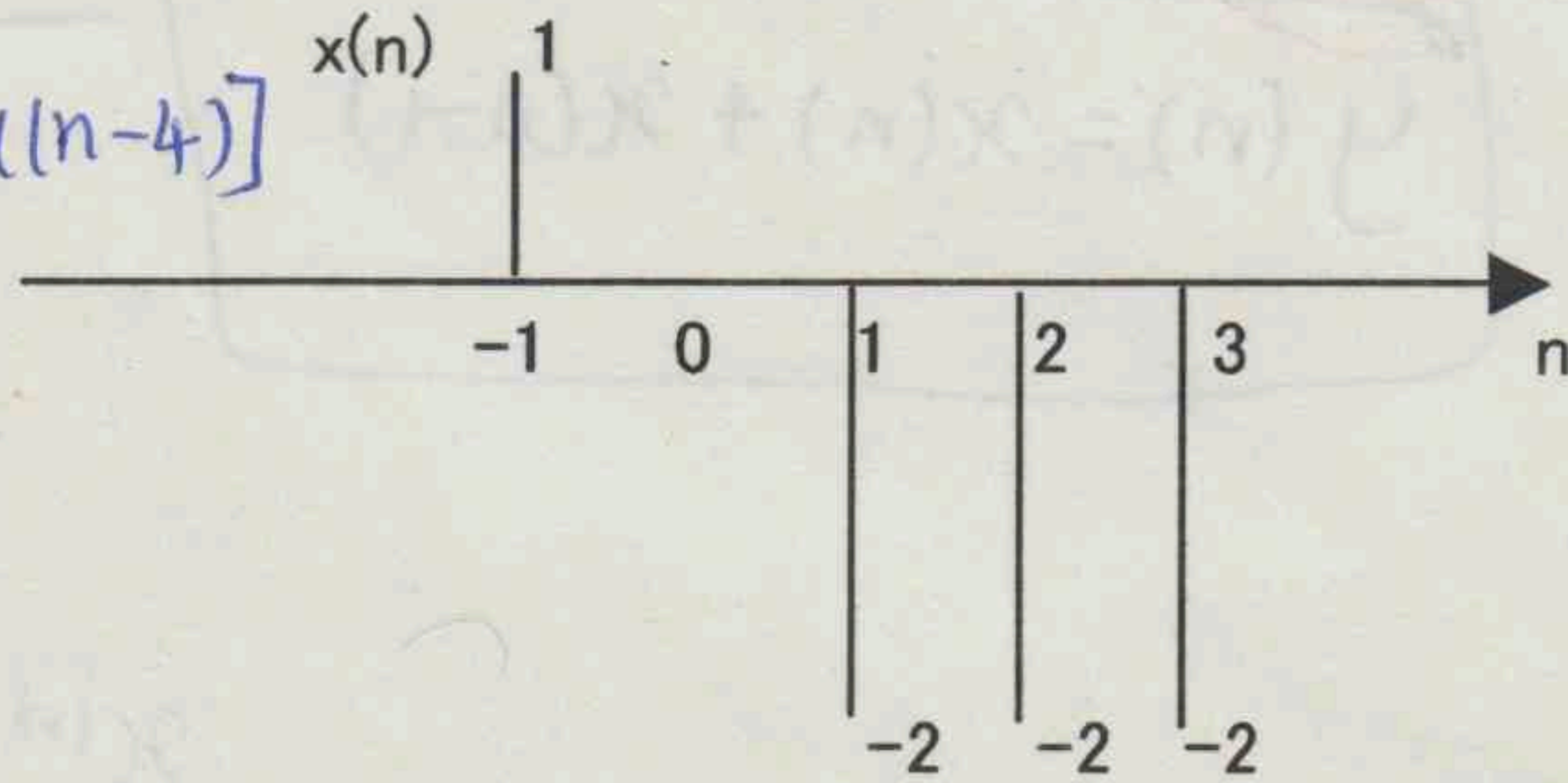
Faculty of Engineering

Dept. of Information Eng.

Prof. M.R. Asharif

1. 図で信号、 $x(n]$ 、を unit step ( $u(n)$ )、と  $\delta(n)$ 、関数を用いて表現せよ。

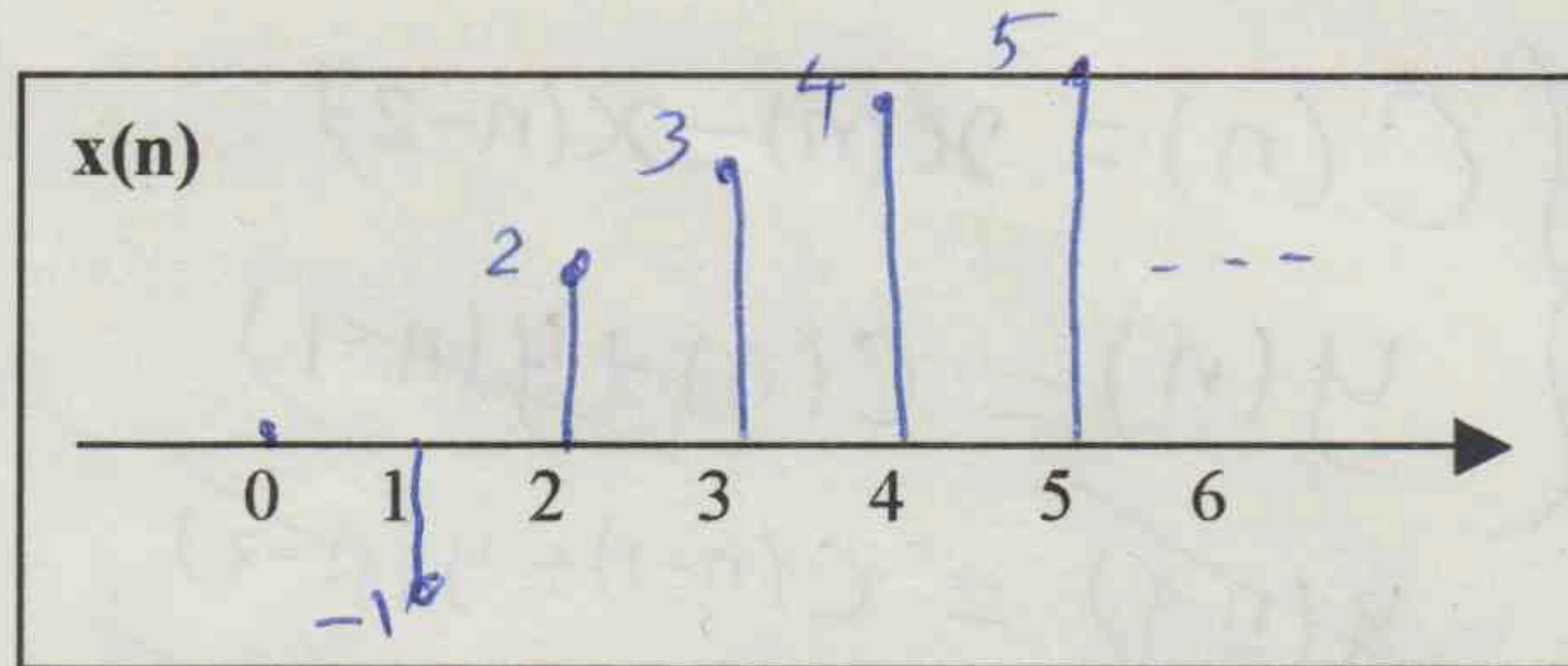
$$x(n) = \delta(n+1) - [2u(n-1) - 2u(n-4)]$$



$$x(n) = \delta(n+1) - 2[u(n-1) - u(n-4)]$$

2. 次の信号の5 サンプルまでをプロットせよ。

$$x(n) = -2\delta(n-1) + nu(n)$$



3. 図に示す離散時間システムのインパルス応答、 $h(n)$ 、を求めよ。

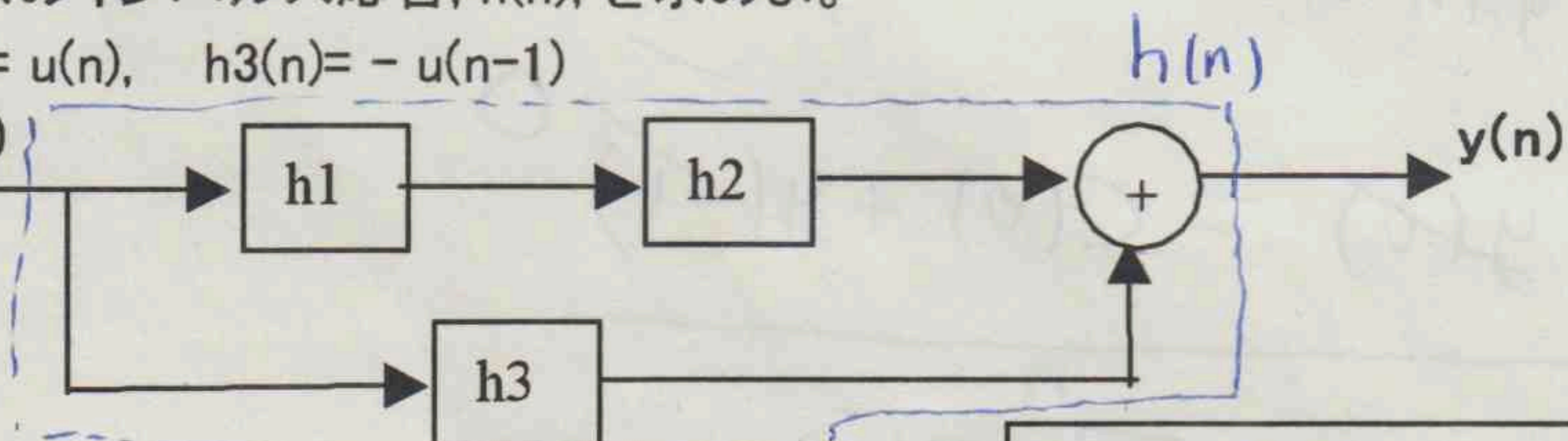
ただし:  $h_1(n) = \delta(n)$ ,  $h_2(n) = u(n)$ ,  $h_3(n) = -u(n-1)$

$$h(n) = h_1(n) * h_2(n) + h_3(n) * x(n)$$

$$h(n) = \delta(n) * u(n) - u(n-1)$$

$$h(n) = u(n) - u(n-1)$$

$$h(n) = \delta(n)$$



$$h(n) = \delta(n)$$

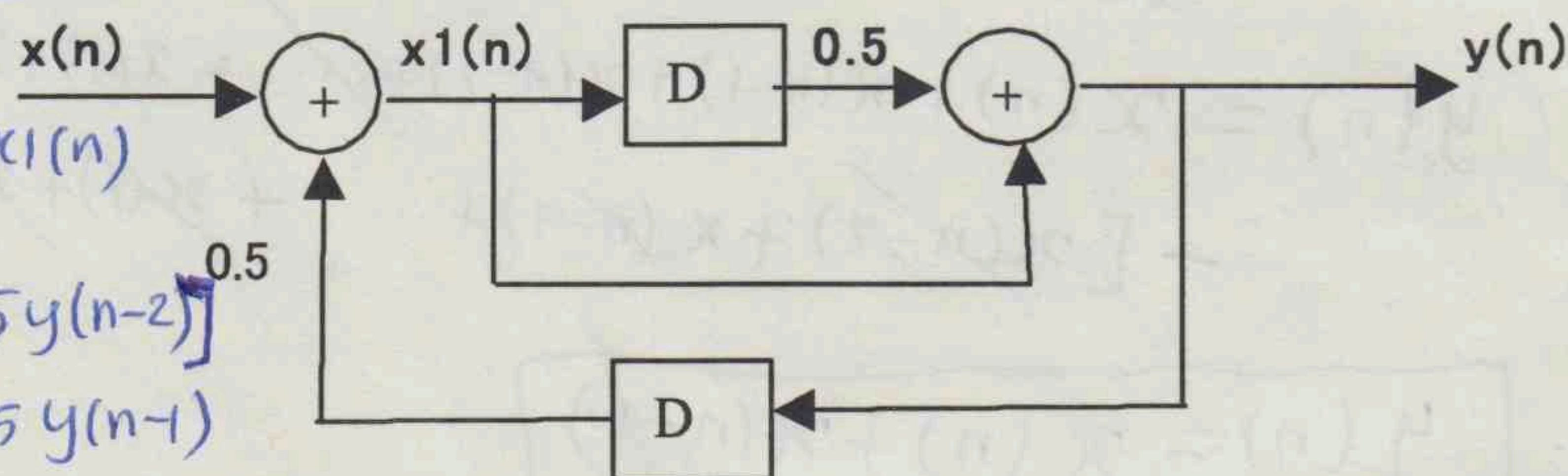
4. 図に示す離散時間システム(IIR Digital Filter) の差分方程式を指出せよ。

$T=1$

$$x_1(n) = x(n) + 0.5y(n-1)$$

$$y(n) = 0.5x_1(n-1) + x_1(n)$$

$$y(n) = 0.5[x(n-1) + 0.5y(n-2)] + x(n) + 0.5y(n-1)$$



$$y(n) = x(n) + 0.5x(n-1) + 0.5y(n-1) + 0.25y(n-2)$$

5. 以下 2 個の入出力を示すシステムの線形性、時不変性、因果性、を判定し、○か×で示せよ。

1)  $y(nT) = e^{-n} x(nT+T)$

2)  $y(nT) = 1 + x(nT)$

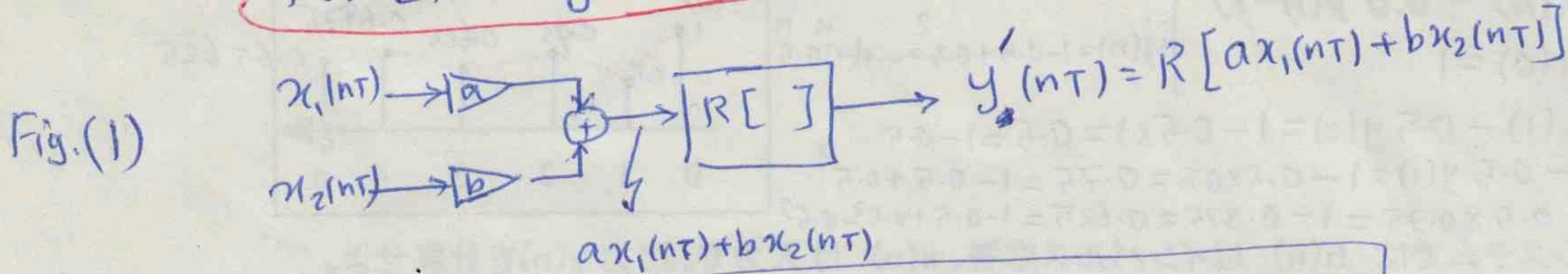
	Linearity,	Shift Invariance,	Causality
1)	○	×	×
2)	×	○	○



5) -

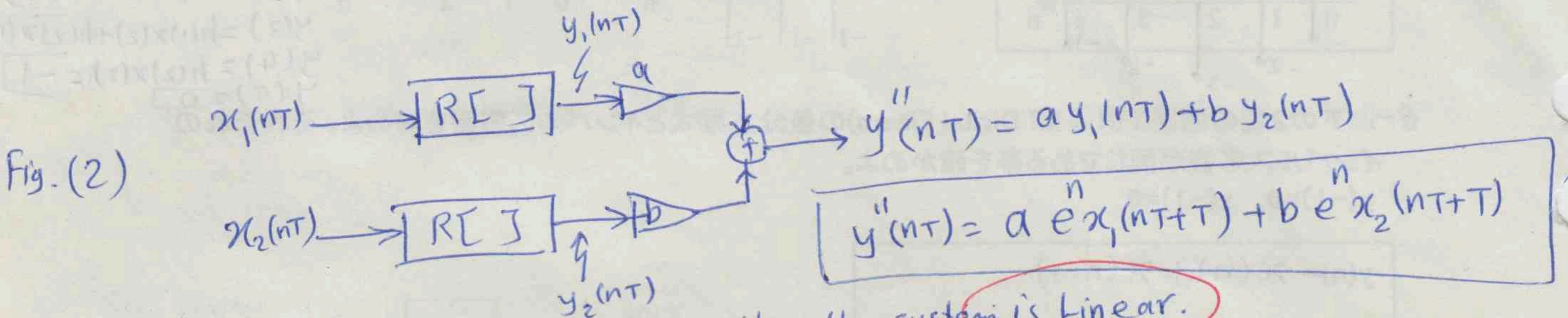
$$1- y(nT) = e^n x(nT+T) = R[x(nT)]$$

For Linearity investigation



$$y_1'(nT) = e^n [ax_1(nT+T) + bx_2(nT+T)] \quad (1)$$

Next, we investigate the following structure:



$$y_2''(nT) = a e^n x_1(nT+T) + b e^n x_2(nT+T)$$

Eq. (1) and Eq. (2) are same, then the system is Linear.

2-  $y(nT) = 1 + x(nT)$   
Now, let's try Linearity for the above system:

From structure, in Fig. 1:

$$y_1'(nT) = R[ax_1(nT) + bx_2(nT)] = 1 + ax_1(nT) + bx_2(nT) \quad (3)$$

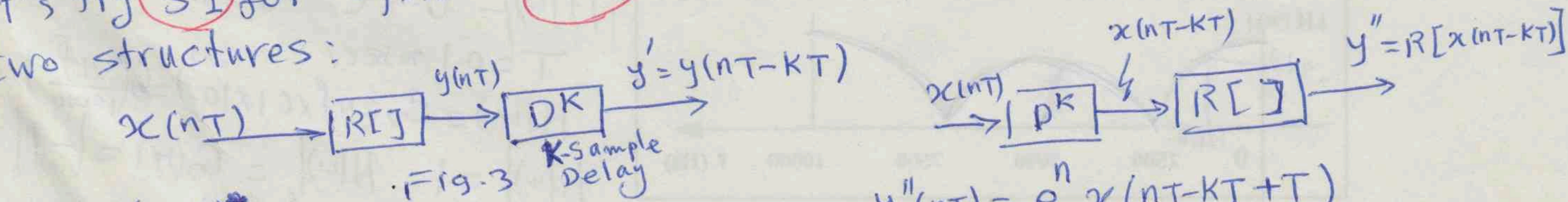
From structure, in Fig. 2:

$$y_2''(nT) = ay_1(nT) + by_2(nT) = a[1 + x_1(nT)] + b[1 + x_2(nT)]$$

$$y_2''(nT) = a + ax_1(nT) + b + bx_2(nT) \quad (4)$$

Eq. (3) is not equal to Eq. (4), then this system is not Linear.

Let's try SI for system in (1): For SI we should compare the following two structures:



$$y_1'(nT) = e^n x(nT - kT + T)$$

Then:  $y_1' \neq y_2'' \Rightarrow$  System is not S.I.

For system in (2)

$$y_1'(nT) = 1 + x(nT - kT)$$

$$y_2''(nT) = 1 + x(nT - kT)$$

Then  $y_1'(nT) = y_2''(nT) \Rightarrow$  this system is S.I.

For Causality, because both systems are not LSI, just we search whether  $y(nT)$  is dependent on present and past samples of  $x(nT)$  or not:

For system (1) depends on future samples of  $x(nT)$ , then not Causal, but system (2) is Causal.



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$$y(n) = \frac{1}{1-0.5} = 0.6666\dots$$

6. 次の LSI システムでは、 $x(n] = u(n]$  は入力で、出力  $y(n]$  の 5 サンプルを計算せよ。

$$y(-1) = 0$$

$$y(n] = x(n] - 0.5 y(n-1]$$

$$y(0] = u(0] = 1$$

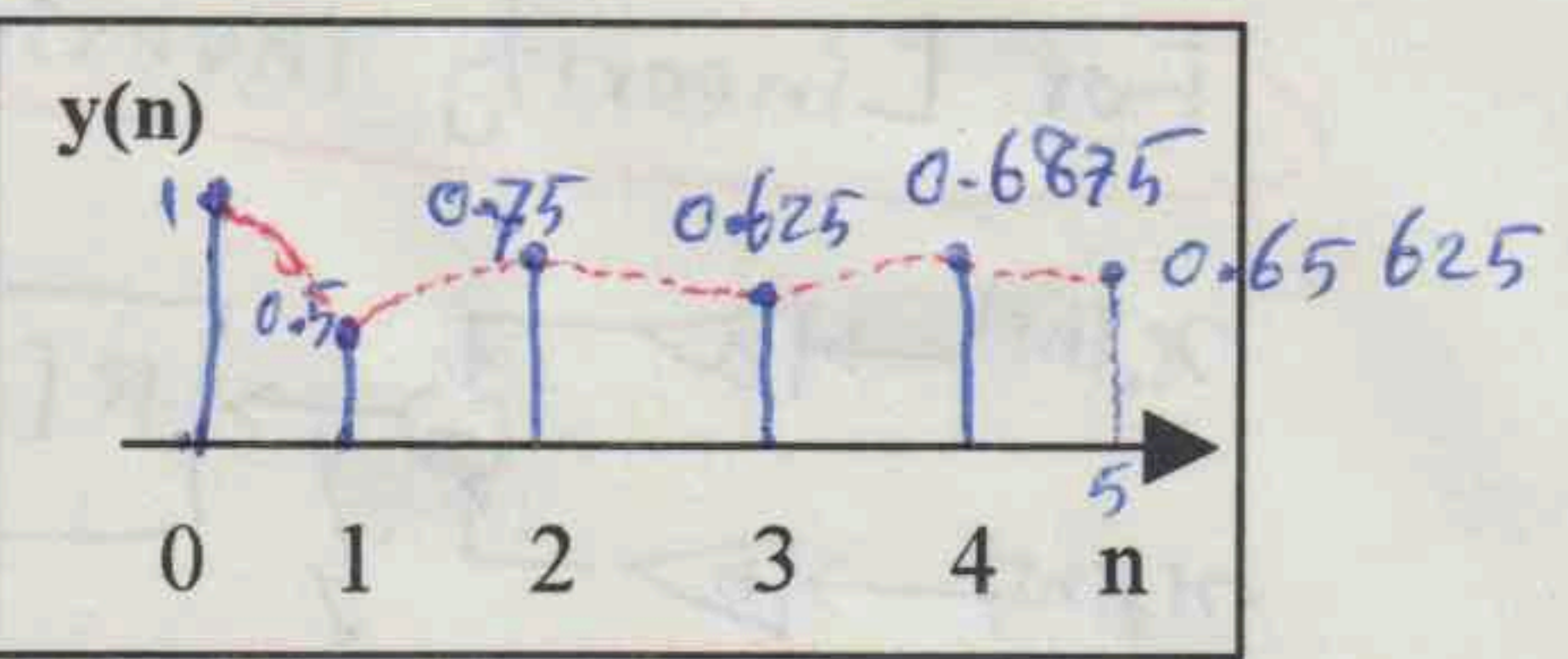
$$y(1] = u(1] - 0.5 y(0] = 1 - 0.5 \times 1 = 0.5 = 1 - 0.5$$

$$y(2] = 1 - 0.5 y(1] = 1 - 0.5 \times 0.5 = 0.75 = 1 - 0.5 + 0.5^2$$

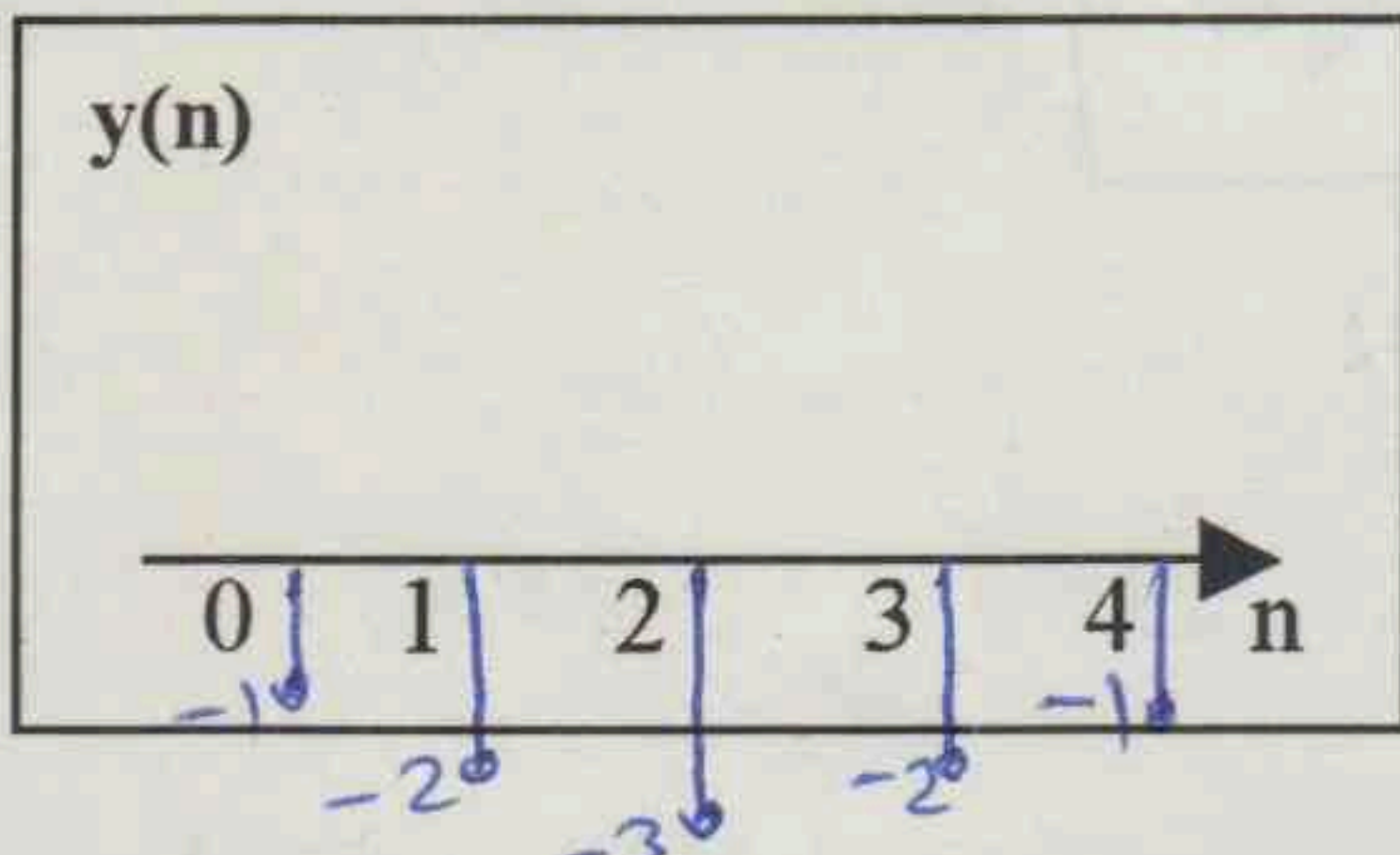
$$y(3] = 1 - 0.5 \times 0.75 = 1 - 0.375 = 0.625 = 1 - 0.5 + 0.5^2 - 0.5^3$$

$$y(4] = 1 - 0.5 + 0.5^2 - 0.5^3 + 0.5^4$$

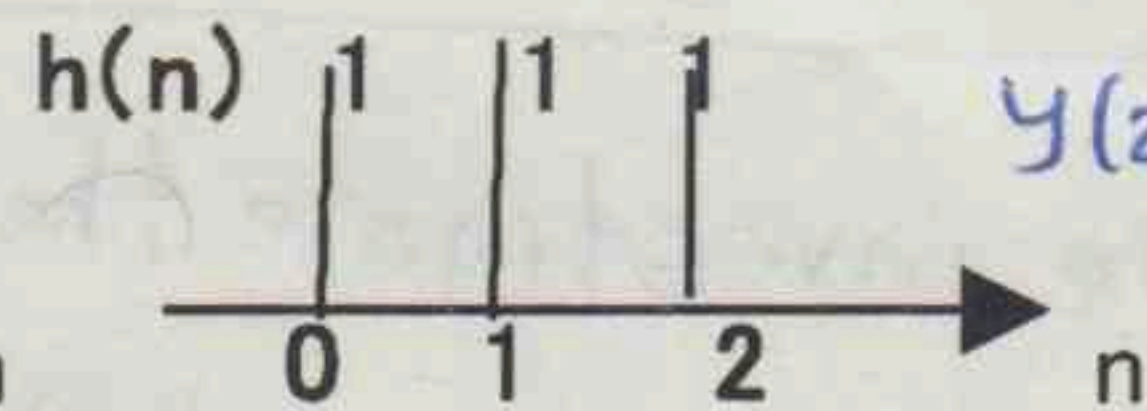
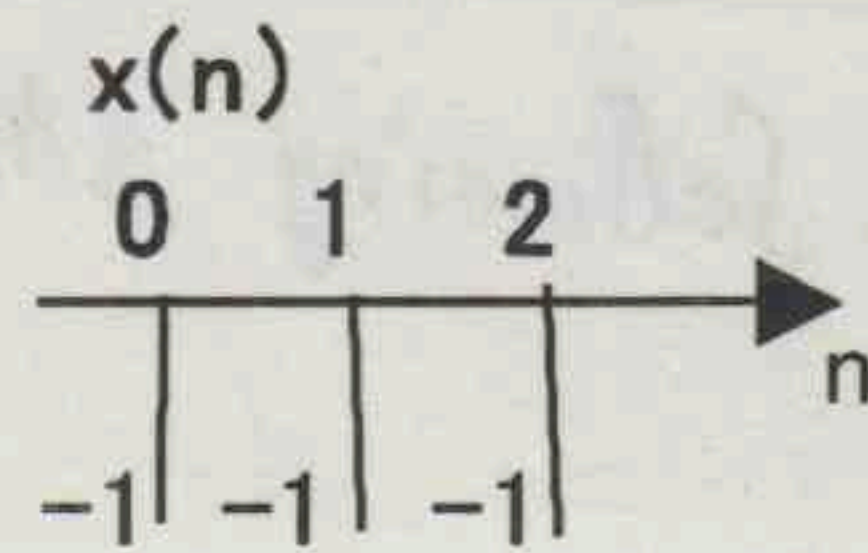
$$y(n] = 1 - 0.5 + 0.5^2 - \dots + (-1)^n 0.5^n$$



7. 次の LSI システムでは  $h(n]$  はインパルス応答、 $x(n]$  は入力で、出力  $y(n]$  を計算せよ。



$$y(n] = \sum_{k=0}^4 h(k] x(n-k], \quad y(0] = h(0] x(0] = -1, \quad y(1] = h(0] x(1] + h(1] x(0]$$



$$y(2] = h(0] x(2] + h(1] x(1] + h(2] x(0]$$

$$y(2] = -1 - 1 - 1 = -3$$

$$y(3] = h(1] x(2] + h(2] x(1] = -2$$

$$y(4] = h(2] x(2] = -1$$

$$y(5] = 0$$

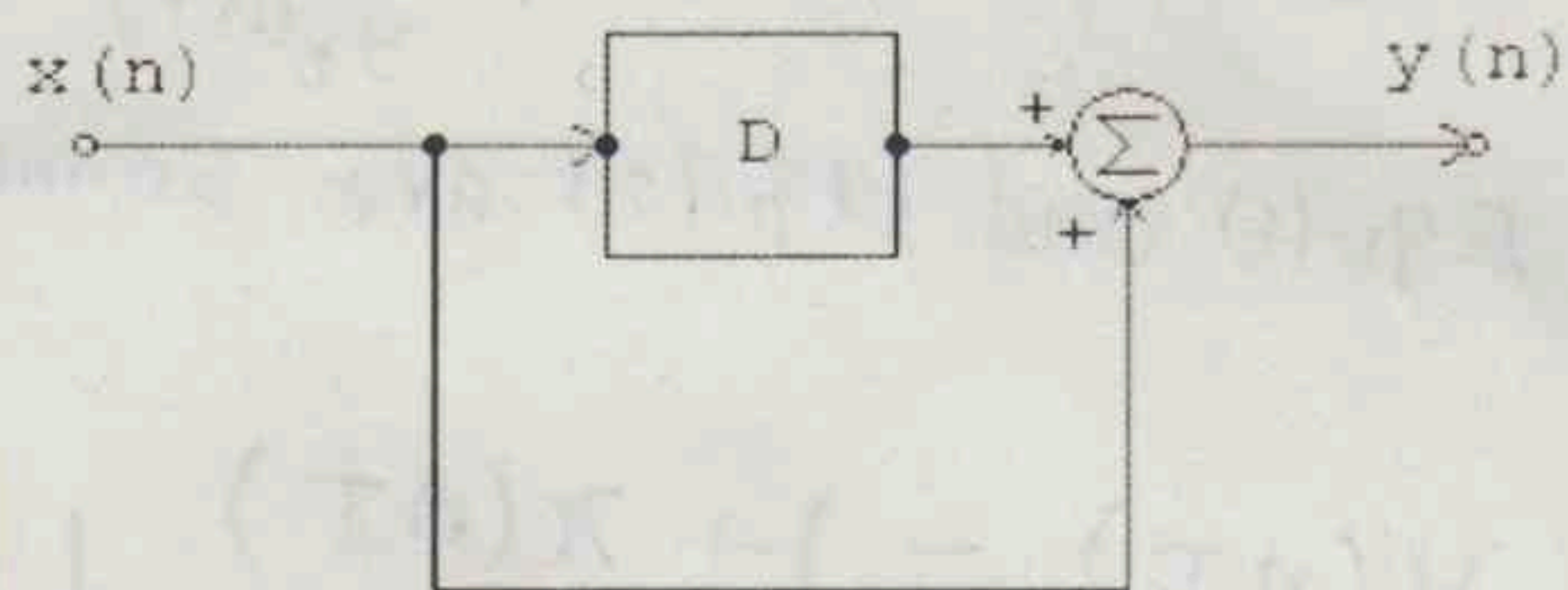
8. 以下の 2 個の回路 (FIR & IIR Digital Filters) の差分方程式とインパルス応答を求めよ。それぞれの

インパルス応答が同じであることを確かめよ。

$$y(-1) = 0, \quad x(-1) = 0$$

$$y(n] = x(n] + x(n-1]$$

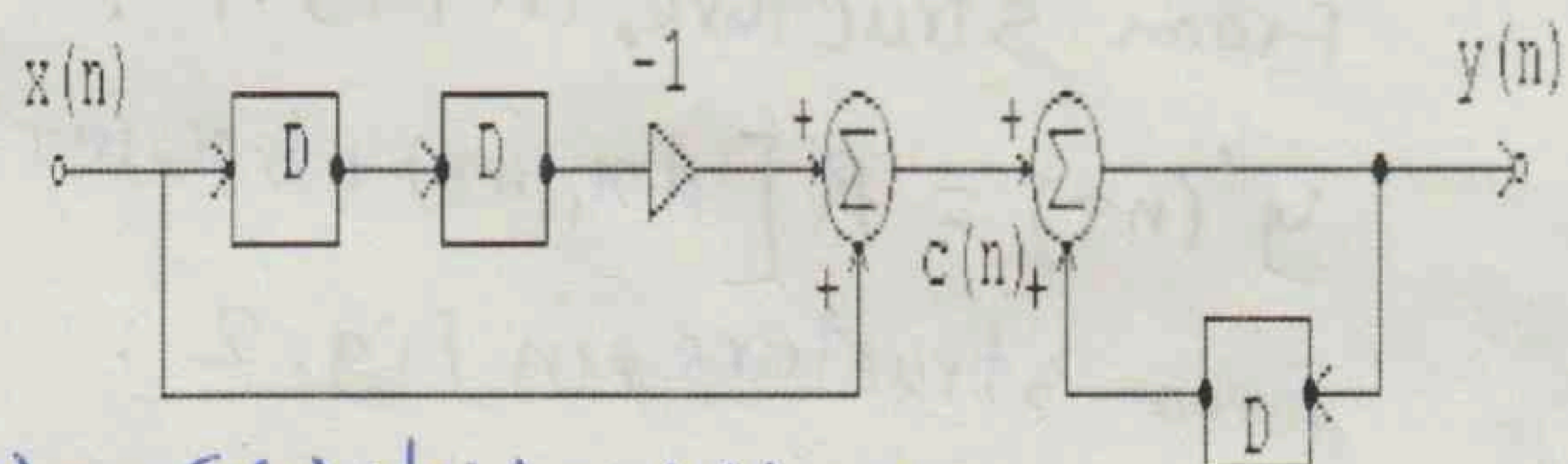
$$h(n] = \delta(n] + \delta(n-1]$$



$h(0] = 1, \quad h(1] = 1, \quad h(2] = 0, \dots$   
 [more detail in previous page]

$$y(n] = x(n] - x(n-2] + y(n-1]$$

$$h(n] = \delta(n] + \delta(n-1]$$



$$x(n] = \delta(n]$$

$$h(n] = \delta(n] - \delta(n-2] + h(n-1]$$

$$h(0] = 1$$

$$h(1] = h(0] = 1$$

$$h(2] = -\delta(0] + h(1] = -1 + 1 = 0$$

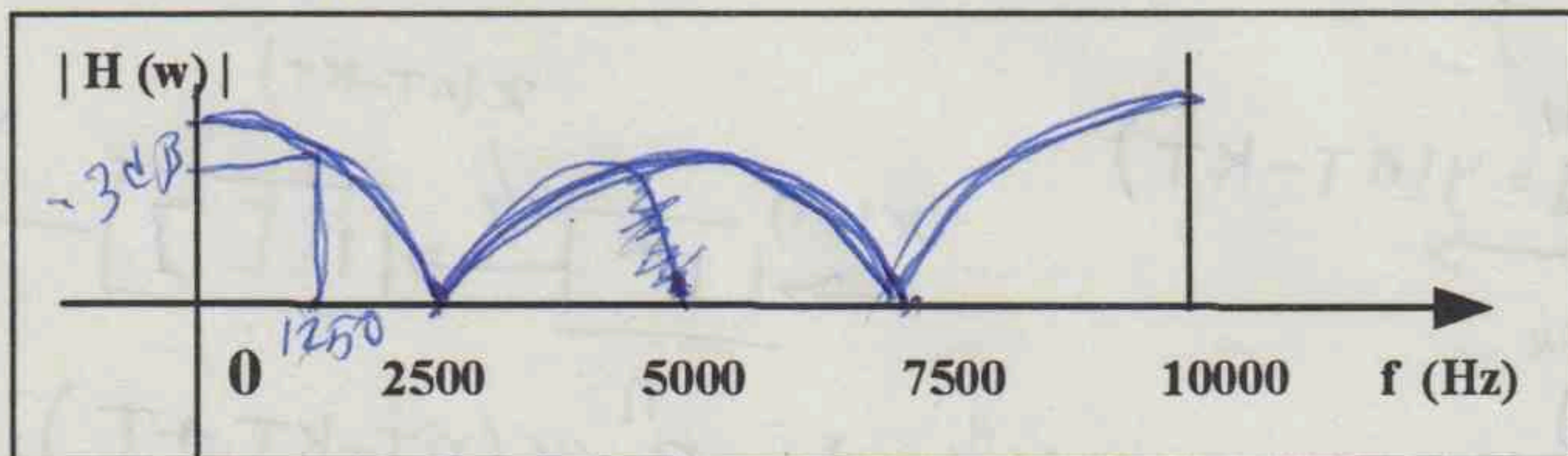
$$h(3] = h(2] = 0$$

9. 次の離散時間システムのフーリエ変換  $|H(\omega)]$  と  $\text{Arg}[H(\omega)]$  を求めよ。

$$h(nT] = 0.5\delta(nT + T] + 0.5\delta(nT - T]$$

$T = 0.1 \text{ ms}$  の時、 $|H(\omega)]$  をプロットせよ。

$f = 2500 \text{ Hz}$  で  $|H(\omega)]$  (dB) を求めよ。



$$|H(\omega)] = |\cos \omega T|$$

$$\text{arg}[H(\omega)] = 0, \pi$$

$$20 \log_{10} |H(\omega)] = -3 \text{ dB} \quad \text{at } f = 2500$$

$$H(\omega) = \sum_{n=-1}^1 h(nT) e^{-j\omega nT}$$

$$|H(\omega)] = 0.5 e^{j\omega T} + 0.5 e^{-j\omega T} = |\cos \omega T|$$

$$T = 0.1 \text{ msec.}$$

$$|H(\omega)] = \cos(2\pi f \times 0.1 \times 10^{-3}) = \cos\left(\frac{2\pi f}{10000}\right)$$

$$|H(\omega)]_{f=0} = 1, \quad |H(\omega)]_{f=5000} = \cos(\pi) = -1 = 1$$

$$|H(\omega)]_{f=10000} = \cos(2\pi) = 1$$

$$|H(\omega)]_{f=2500, 7500} = 0$$

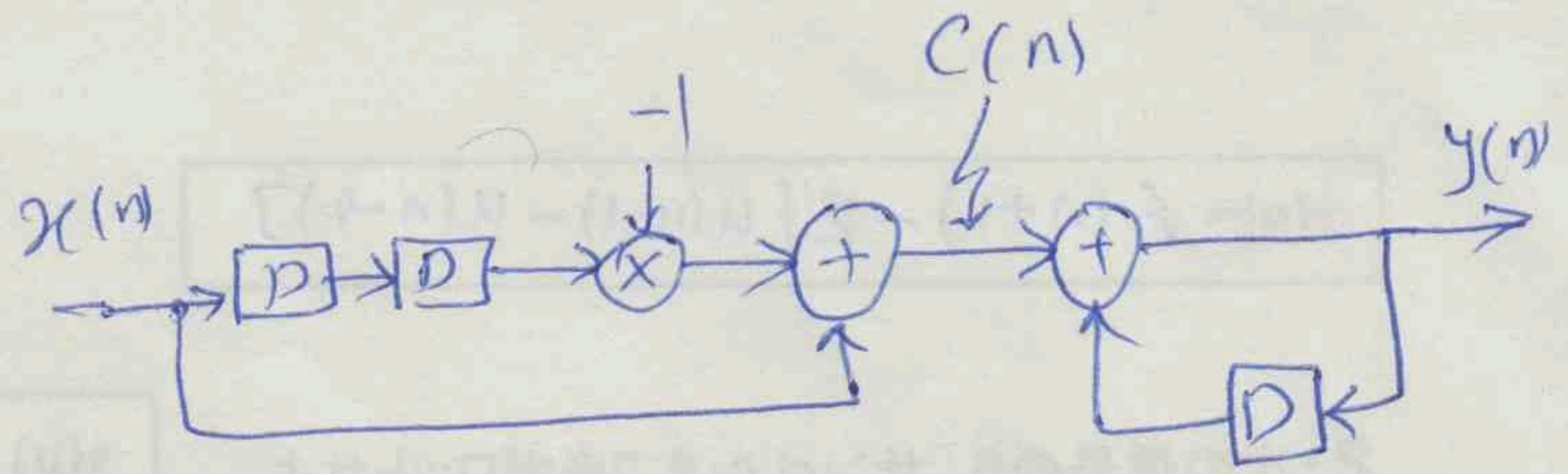
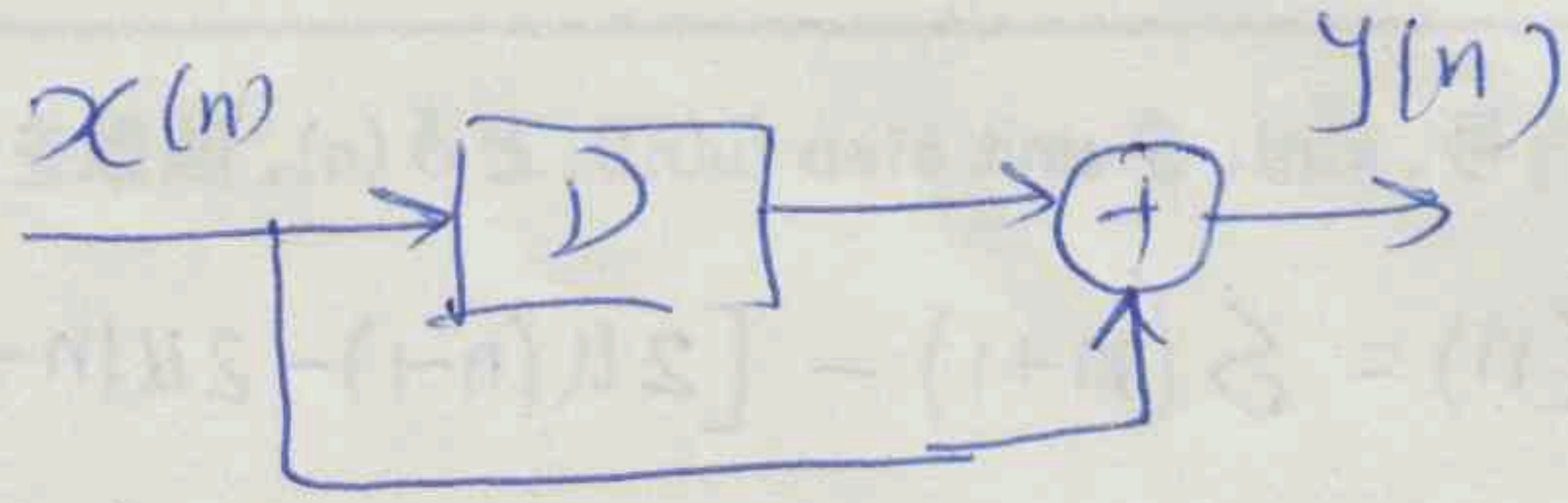
$$|H(\omega)]_{f=1250} = \cos\left(\frac{2\pi \times 1250}{10000}\right) = \cos\left(\frac{\pi}{4}\right) = \frac{\sqrt{2}}{2}$$

$$20 \log_{10} \frac{\sqrt{2}}{2} = -10 \log_{10} 2 = -3 \text{ dB}$$



8-

$$y(n] = x(n) + x(n-1]$$



$$\begin{cases} C(n) = x(n) - x(n-2] \\ y(n) = C(n) + y(n-1] \\ y(n-1] = C(n-1] + y(n-2] \\ y(n-2] = C(n-2] + y(n-3] \\ \vdots \\ y(0) = C(0) + y(-1] \end{cases}$$

$$y(n) = \sum_{i=0}^n C(i)$$

$$y(n) = \sum_{i=0}^n x(i) - x(i-2]$$

$$y(n) = x(n) + x(n-1] + x(n-2] + \dots + x(1) + x(0) - [x(n-2] + x(n-3] + \dots + x(1) + x(0)]$$

$$y(n) = x(n) + x(n-1]$$

Then, two circuits are equal.