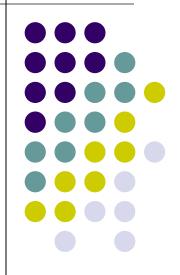
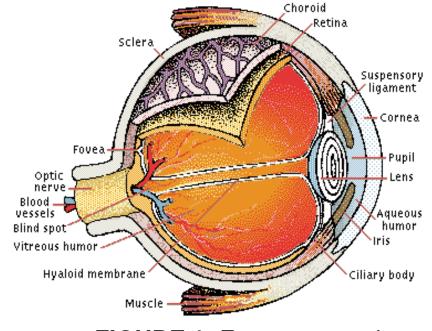
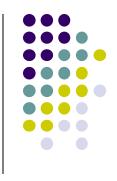
Digital Image Processing:



EYE PHYSIOLOGY

 A conceptual technique for the establishment of a model of the human visual system would be to perform a physiological analysis of the eye, the nerve paths to the brain, and those parts of the brain involved in visual perception.





EYE PHYSIOLOGY



Figure 1 shows the horizontal cross section of a human eyeball. The front of the eye is covered by a transparent surface called the *cornea*. The remaining outer cover, called the *sclera*, is composed of a fibrous coat that surrounds the *choroid*, a layer containing blood capillaries. Inside the choroid is the *retina*, which is composed of two types of receptors: *rods* and *cones*. Nerves connecting to the retina leave the eyeball through the *optic nerve bundle*. Light entering the cornea is focused on the retina surface by a *lens* that changes shape under muscular control to perform proper focusing of near and distant objects. An *iris* acts as a diaphram to control the amount of light entering the eye.

EYE PHYSIOLOGY

• An eye contains about 6.5 million cones and 100 million rods distributed over the retina Figure 2 shows the distribution of rods and cones over a horizontal line on the retina. At a point near the optic nerve called the *fovea*, the density of cones is greatest.

This is the region of sharpest photopic vision. There are no rods or cones in the vicinity of the optic nerve, and hence the eye has a blind spot in this region.

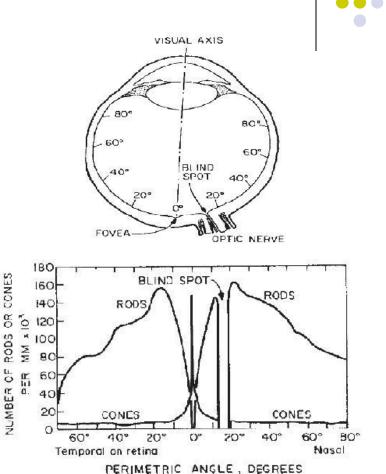


FIGURE 2. Distribution of rods and cones on the retina

Visual Perception: Human Eye

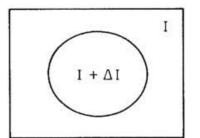
- 1. The *lens* contains 60-70% water, 6% of fat.
- 2. The *iris* diaphragm controls amount of light that enters the eye.
- 3. Light receptors in the retina
 - About 6-7 millions *cones* for bright light vision called *photopic*
 - Density of cones is about 150,000 elements/mm².
 - Cones involve in color vision.
 - Cones are concentrated in *fovea* about 1.5x1.5 mm².
 - About 75-150 millions *rods* for dim light vision called *scotopic*
 - Rods are sensitive to low level of light and are not involved color vision.
- 4. *Blind spot* is the region of emergence of the optic nerve from the eye.

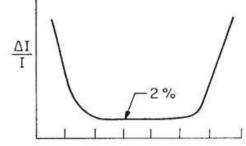




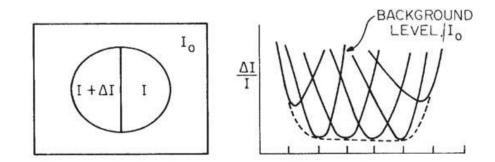
VISUAL PHENOMENA

The response of the eye to changes in the intensity of illumination is known to be nonlinear. Consider a patch of light of intensity surrounded by a background of intensity *I*. The just noticeable difference is to be determined as a function of *I*. Over a wide range of intensities, it is found that the ratio , called the *Weber fraction*, is nearly constant at a value of about 0.02.





INTENSITY, I



INTENSITY, I

FIGURE: Contrast sensitivity measurements.

Modulation transfer function (MTF)

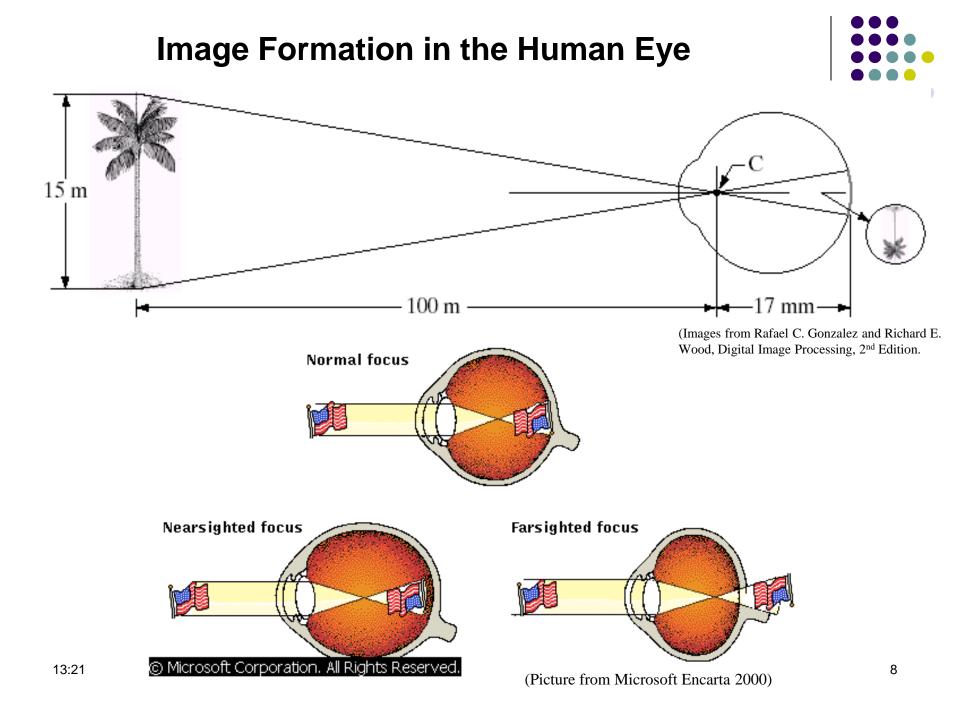
 The ratio of the magnitudes of the Fourier transforms of the input and output signals

$$\frac{\left|\mathcal{I}_{O}(\omega_{x}, \omega_{y})\right|}{\left|\mathcal{I}_{I}(\omega_{x}, \omega_{y})\right|} = \left|\mathcal{H}(\omega_{x}, \omega_{y})\right|$$

is called the *modulation transfer function* (MTF) of the optical system.



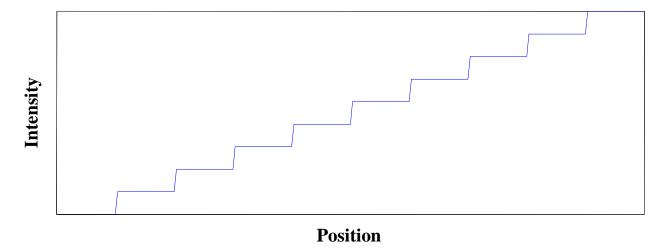
FIGURE: MTF measurements of the human visual system by modulated sine-wave grating.



Brightness Adaptation of Human Eye : Mach Band Effect



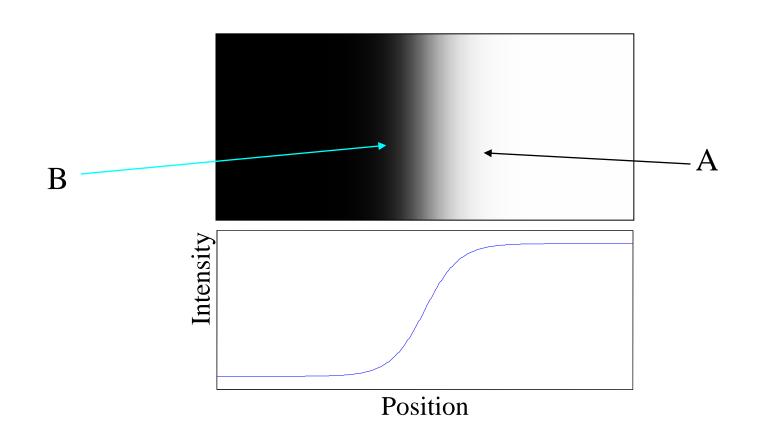




For middle steps human eyes can separate better than lower or higher steps

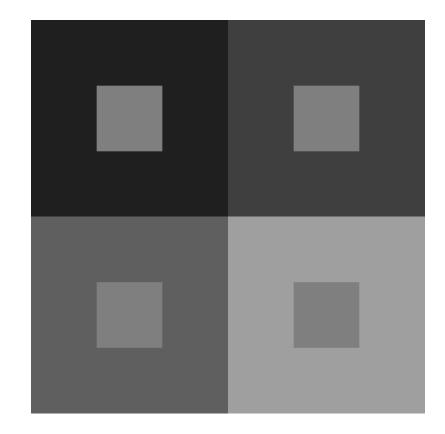
Mach Band Effect (Cont)





In area A, brightness perceived is darker while in area B is brighter. This phenomenon is called *Mach Band Effect*.

Brightness Adaptation of Human Eye : Simultaneous Contrast

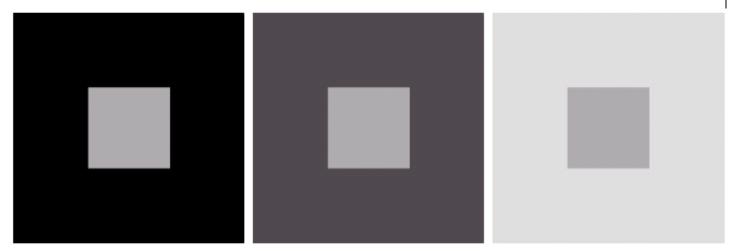




Simultaneous contrast. All small squares have exactly the same intensity but they appear progressively darker as background becomes lighter.

Simultaneous Contrast





a b c

FIGURE 2.8 Examples of simultaneous contrast. All the inner squares have the same intensity, but they appear progressively darker as the background becomes lighter.

12



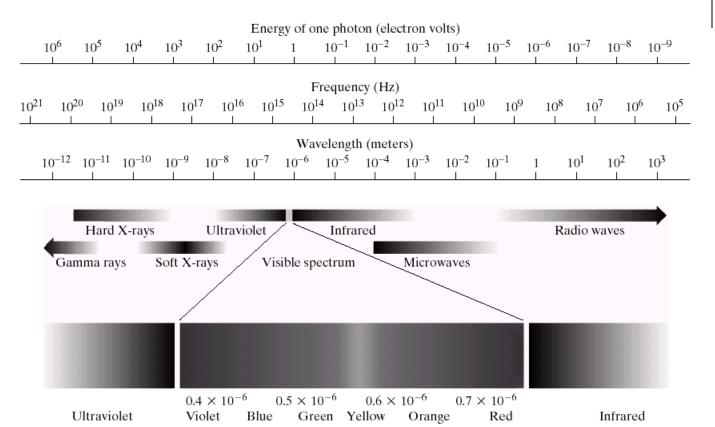
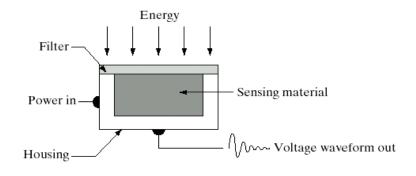
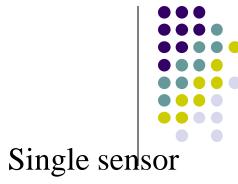


FIGURE 2.10 The electromagnetic spectrum. The visible spectrum is shown zoomed to facilitate explanation, but note that the visible spectrum is a rather narrow portion of the EM spectrum.

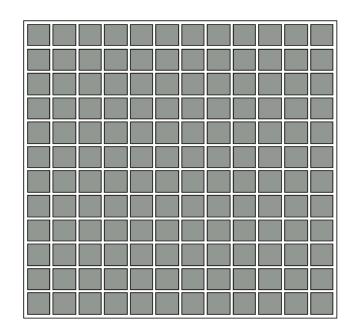
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Image Sensors





Line sensor

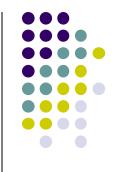


Array sensor

Image sensor typically use in digital camera

(Images from Rafael C. Gonzalez and Richard E. Wood, Digital Image Processing, 2nd Edition.

Fundamentals of Digital Images





- An image: a multidimensional function of spatial coordinates.
- **Spatial coordinate**: (*x*,*y*) for 2D case such as photograph, (x,y,z) for 3D case such as CT scan images (x,y,t) for movies
- The function f may represent intensity (for monochrome images) ₁₃ or color (for color images) or other associated values. 15

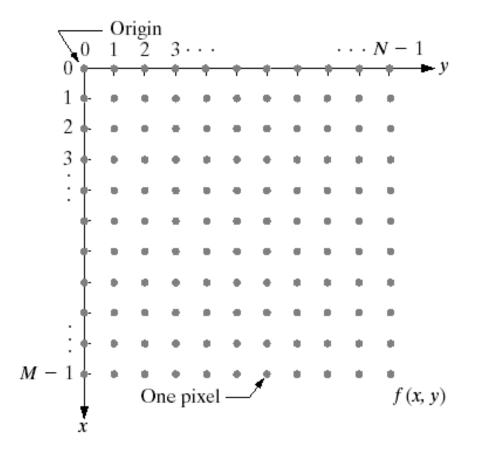
Digital Images



Digital image: an image that has been discretized both in Spatial coordinates and associated value.

- Consist of 2 sets:(1) a point set and (2) a value set
- Can be represented in the form
 I = {(x,a(x)): x ∈ X, a(x) ∈ F}
 where X and F are a point set and value set, respectively.
- An element of the image, (x,a(x)) is called a *pixel* where
 - *x* is called the pixel location and
 - a(x) is the pixel value at the location x

Conventional Coordinate for Image Representation

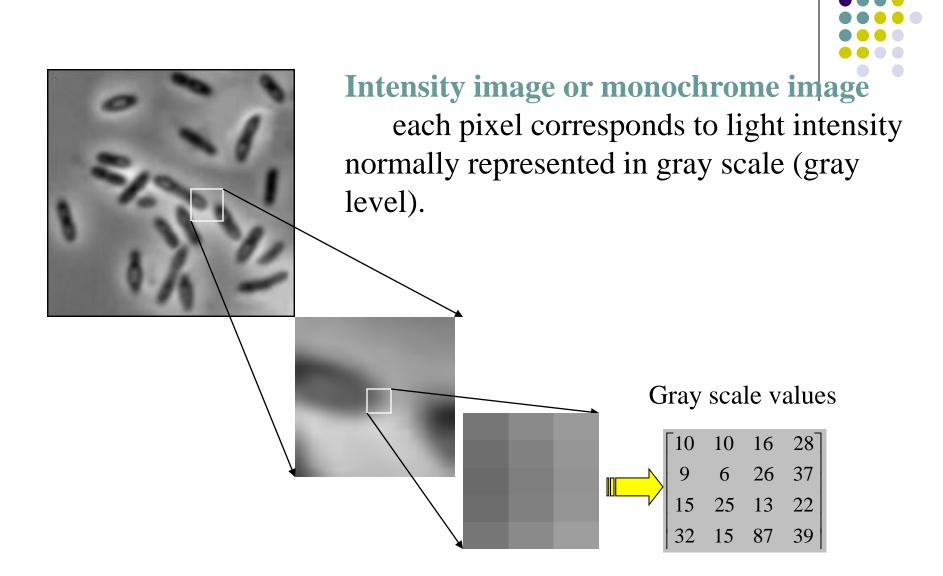




(Images from Rafael C. Gonzalez and Richard E. Wood, Digital Image Processing, 2nd Edition.

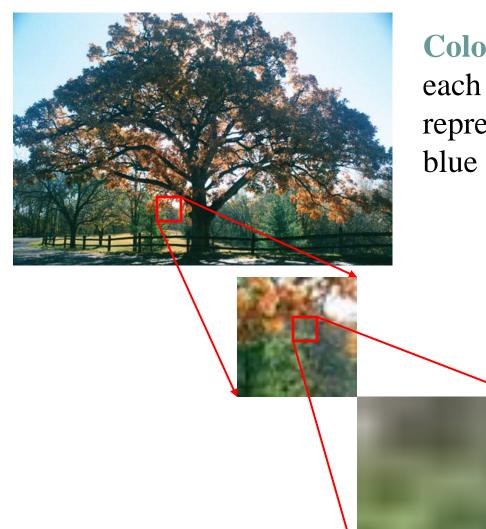
17

Digital Image Types : Intensity Image



Digital Image Types : RGB Image





Color image or RGB image: each pixel contains a vector representing red, green and blue components.

RGB components

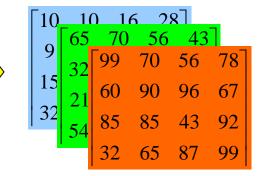


Image Types : Binary Image

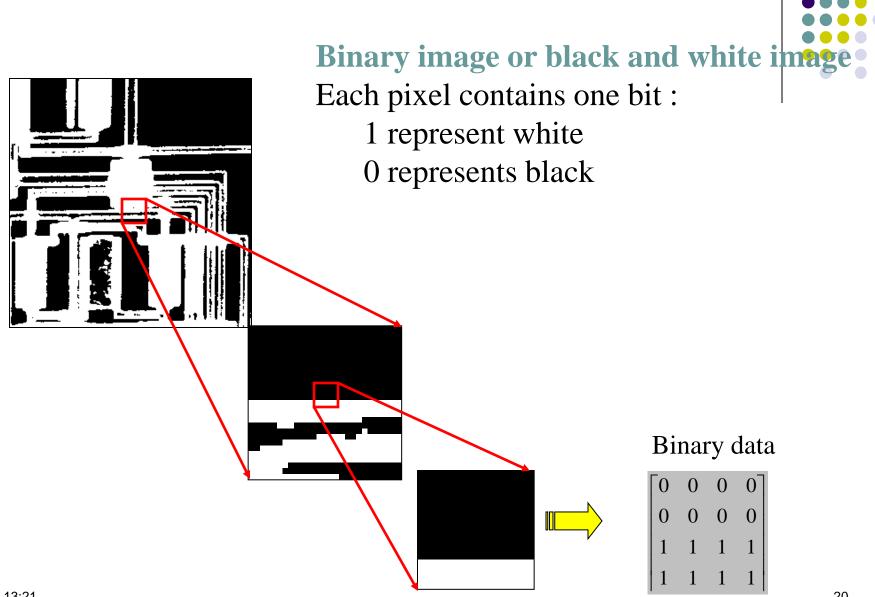


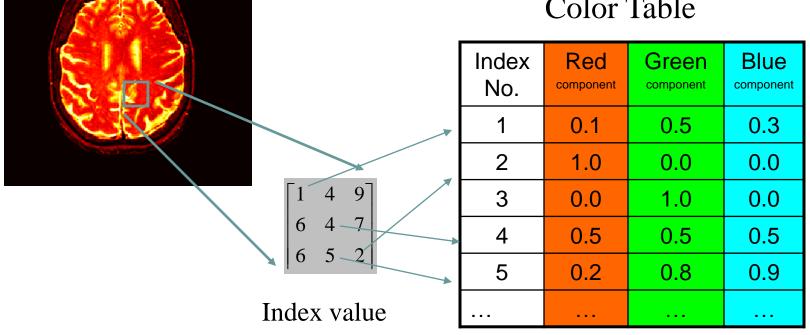
Image Types : Index Image

Index image

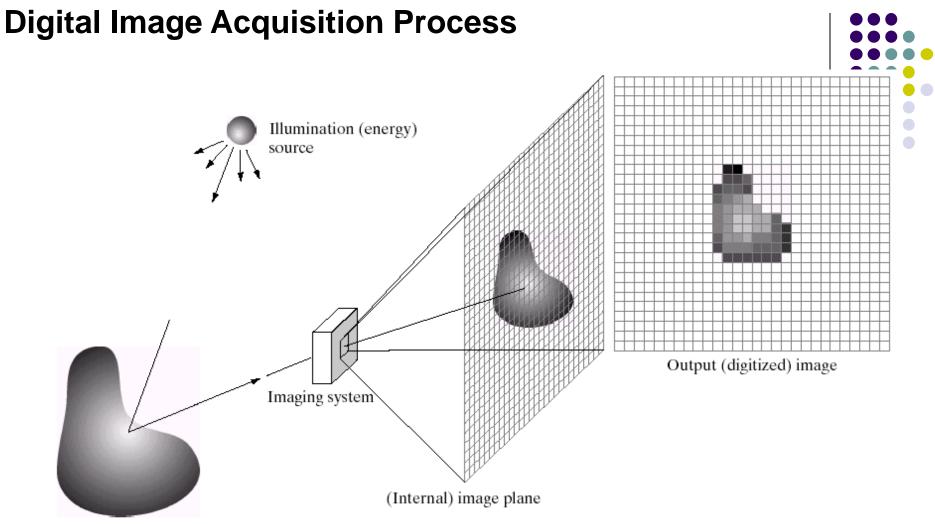
Each pixel contains index number pointing to a color in a color table







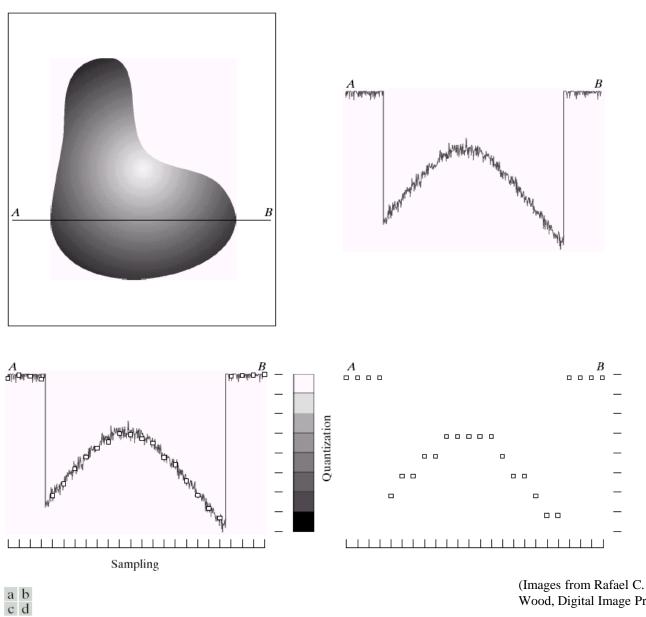
This type image use in CT scan



Scene element

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Generating a Digital Image



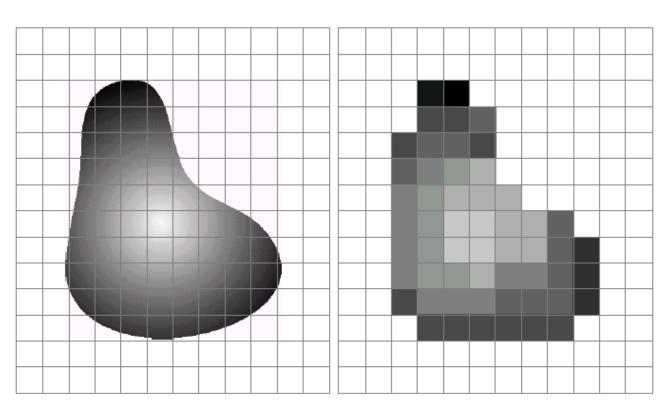


13:21

(Images from Rafael C. Gonzalez and Richard E. Wood, Digital Image Processing, 2nd Edition.

FIGURE 2.16 Generating a digital image. (a) Continuous image. (b) A scan line from *A* to *B* in the continuous image, used to illustrate the concepts of sampling and quantization. (c) Sampling and quantization. (d) Digital scan line.

Image Sampling and Quantization





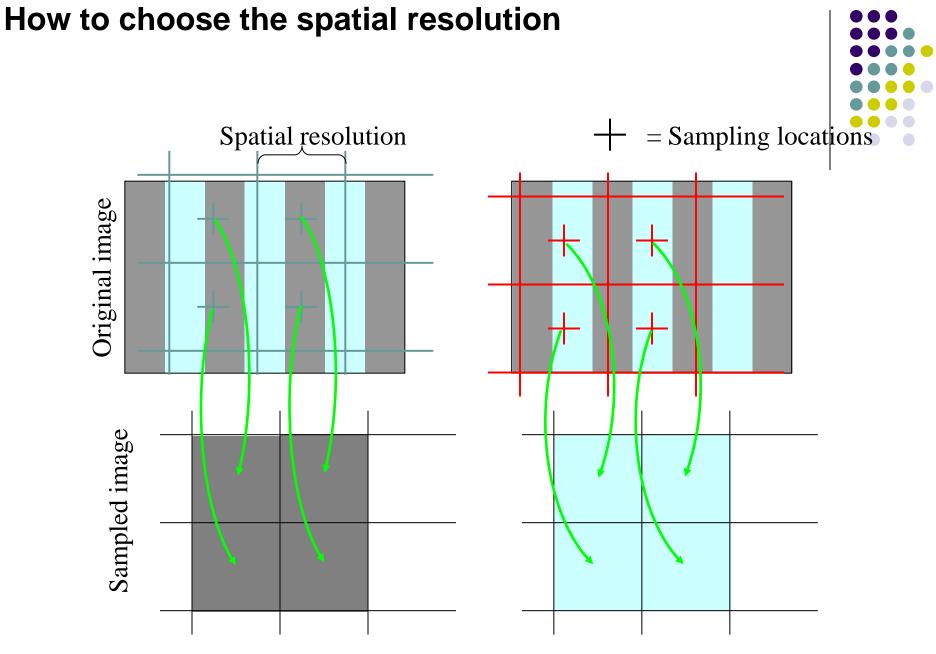
a b

FIGURE 2.17 (a) Continuos image projected onto a sensor array. (b) Result of image sampling and quantization.

Image sampling: discretize an image in the spatial domain

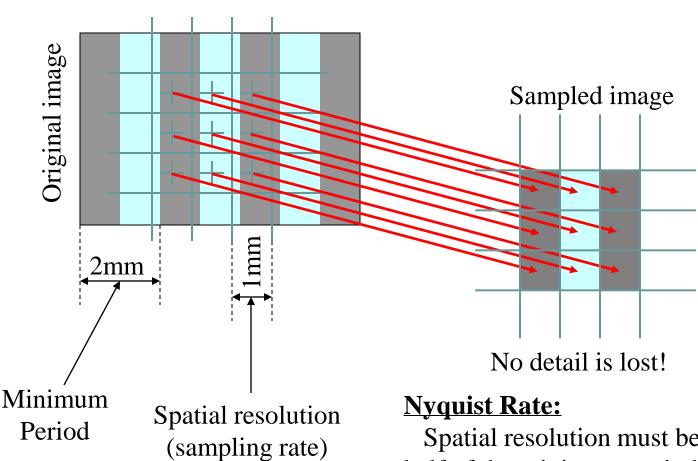
Spatial resolution / image resolution: pixel size or number of pixels $_{24}$

(Images from Rafael C. Gonzalez and Richard E. Wood, Digital Image Processing, 2nd Edition.



Under sampling, we lost some image details!

How to choose the spatial resolution : Nyquist Rate

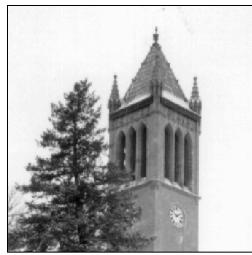




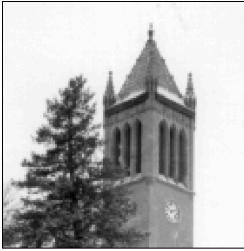
+ = Sampling locations

Spatial resolution must be less or equal half of the minimum period of the image or sampling frequency must be greater or Equal twice of the maximum frequency.

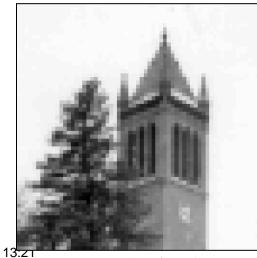
Effect of Spatial Resolution



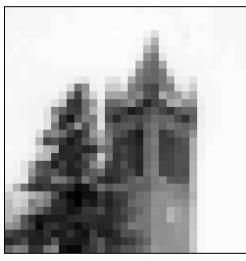
256x256 pixels



128x128 pixels



64x64 pixels



32x32 pixels



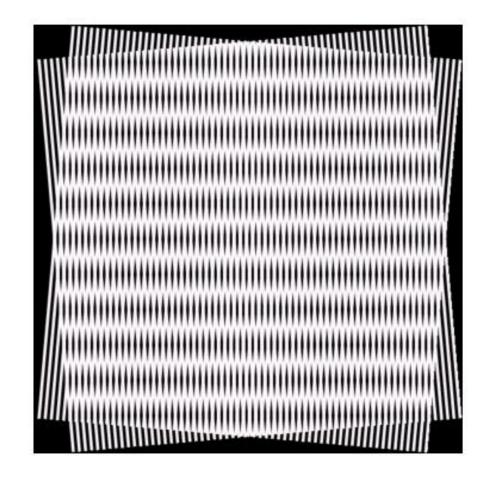
Effect of Spatial Resolution



FIGURE 2.19 A 1024 \times 1024, 8-bit image subsampled down to size 32 \times 32 pixels. The number of allowable gray levels was kept at 256.

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Moire Pattern Effect : Special Case of Sampling



Moire patterns occur when frequencies of two superimposed periodic patterns are close to each other.

(Images from Rafael C. Gonzalez and Richard E. Wood, Digital Image Processing, 2nd Edition.

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Can we increase spatial resolution by interpolation ?

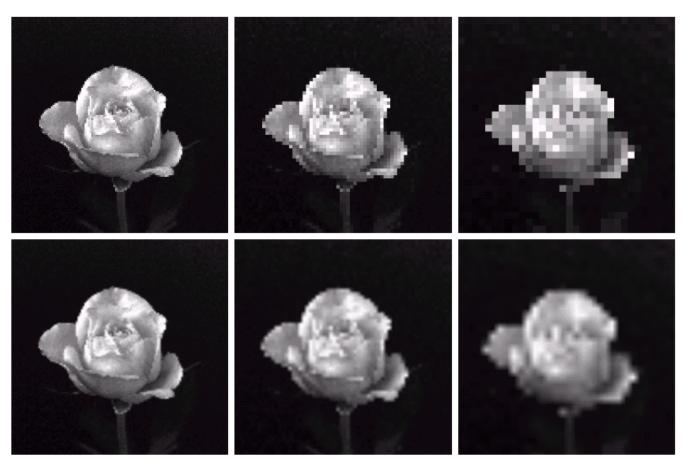




FIGURE 2.25 Top row: images zoomed from 128×128 , 64×64 , and 32×32 pixels to 1024×1024 pixels, using nearest neighbor gray-level interpolation. Bottom row: same sequence, but using bilinear interpolation.

Down sampling is an irreversible process.



(Images from Rafael C. Gonzalez and Richard E. Wood, Digital Image Processing, 2nd Edition.

Effect of Spatial Resolution

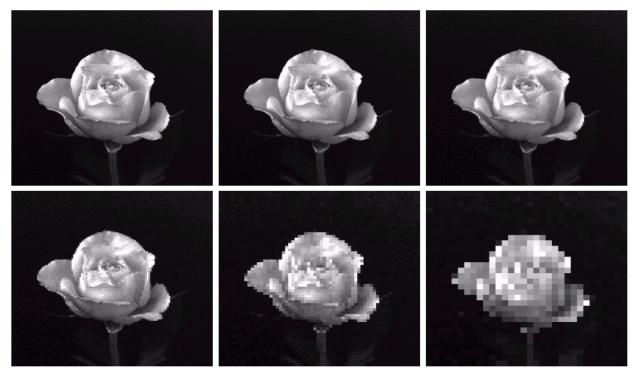






FIGURE 2.20 (a) 1024×1024 , 8-bit image. (b) 512×512 image resampled into 1024×1024 pixels by row and column duplication. (c) through (f) 256×256 , 128×128 , 64×64 , and 32×32 images resampled into 1024×1024 pixels.

Figure 2.20(a) shows a 1024x1024, 256-level digital image of a rose. Figures 2.9(b)-(f) show the results of reducing the spatial resolution form N=1024 to N=512,256,128,64 and 32, respectively.

Image Quantization



Image quantization:

discretize continuous pixel values into discrete numbers

Color resolution/ color depth/ levels:

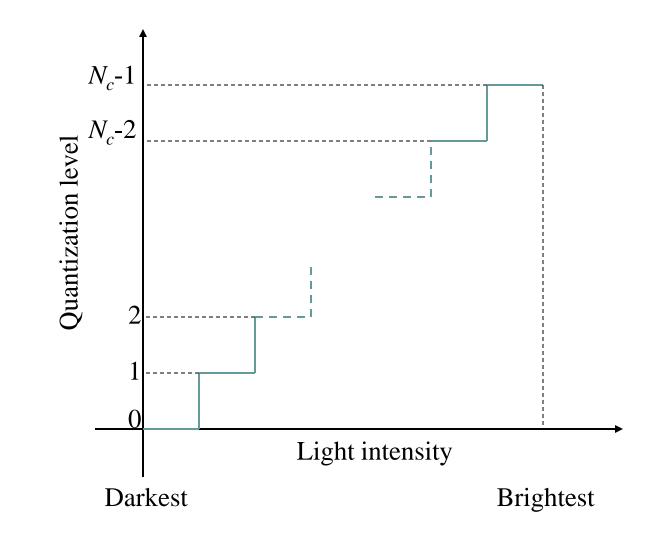
- No. of colors or gray levels or
- No. of bits representing each pixel value
- No. of colors or gray levels N_c is given by

$$N_{c} = 2^{b}$$

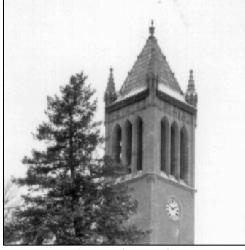
where b = no. of bits

Quantization function





Effect of Quantization Levels



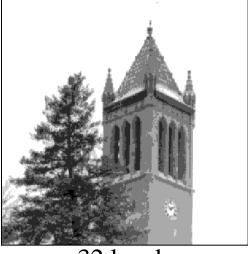
256 levels



64 levels

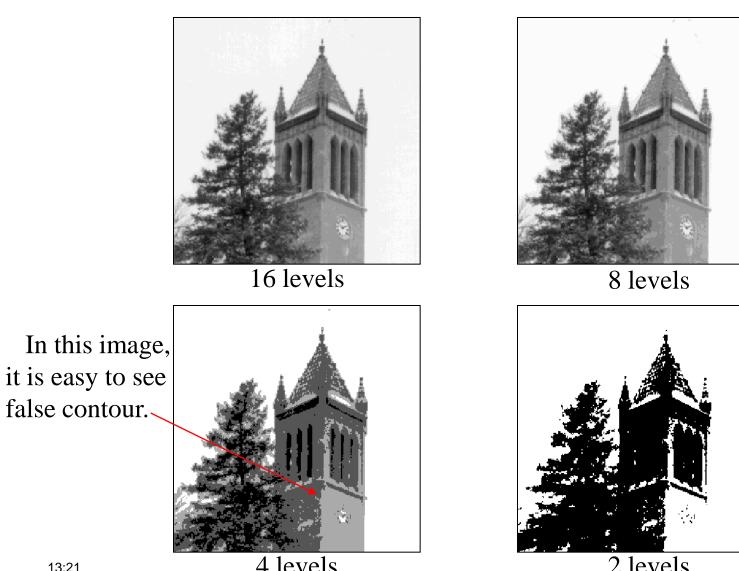


128 levels





Effect of Quantization Levels (cont.)





2 levels

How to select the suitable size and pixel depth of images

The word "suitable" is subjective: depending on "subject"



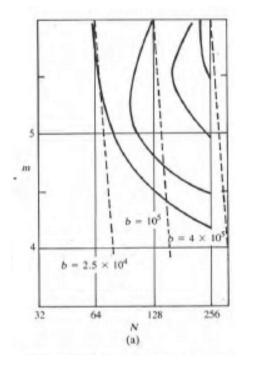
Medium detail image High detail image Low detail image Lena image Cameraman image Crowded image

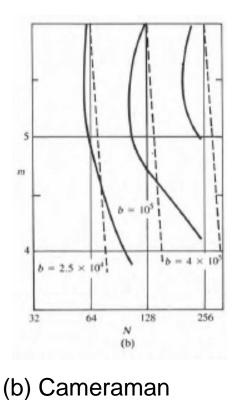
To satisfy human mind

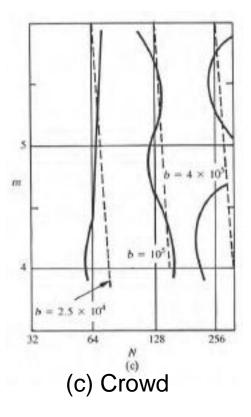
1. For images of the same size, the low detail image may need more pixel depth. 2. As an image detail increases, fewer gray levels may be needed. 36



Isopreference curves







(a) Face

Human vision: Spatial Frequency vs Contrast



