

# An explanation of some feature extractor on generic object recognition

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# Outline

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- ❖ Generic object recognition
  1. Feature points and values
  2. BOF(Bag of Feature)
- ❖ Two feature extractor
  1. SIFT(Scale Invariant Feature Transform)
  2. HOG(Histograms of Oriented Gradients)
- ❖ Conclusion

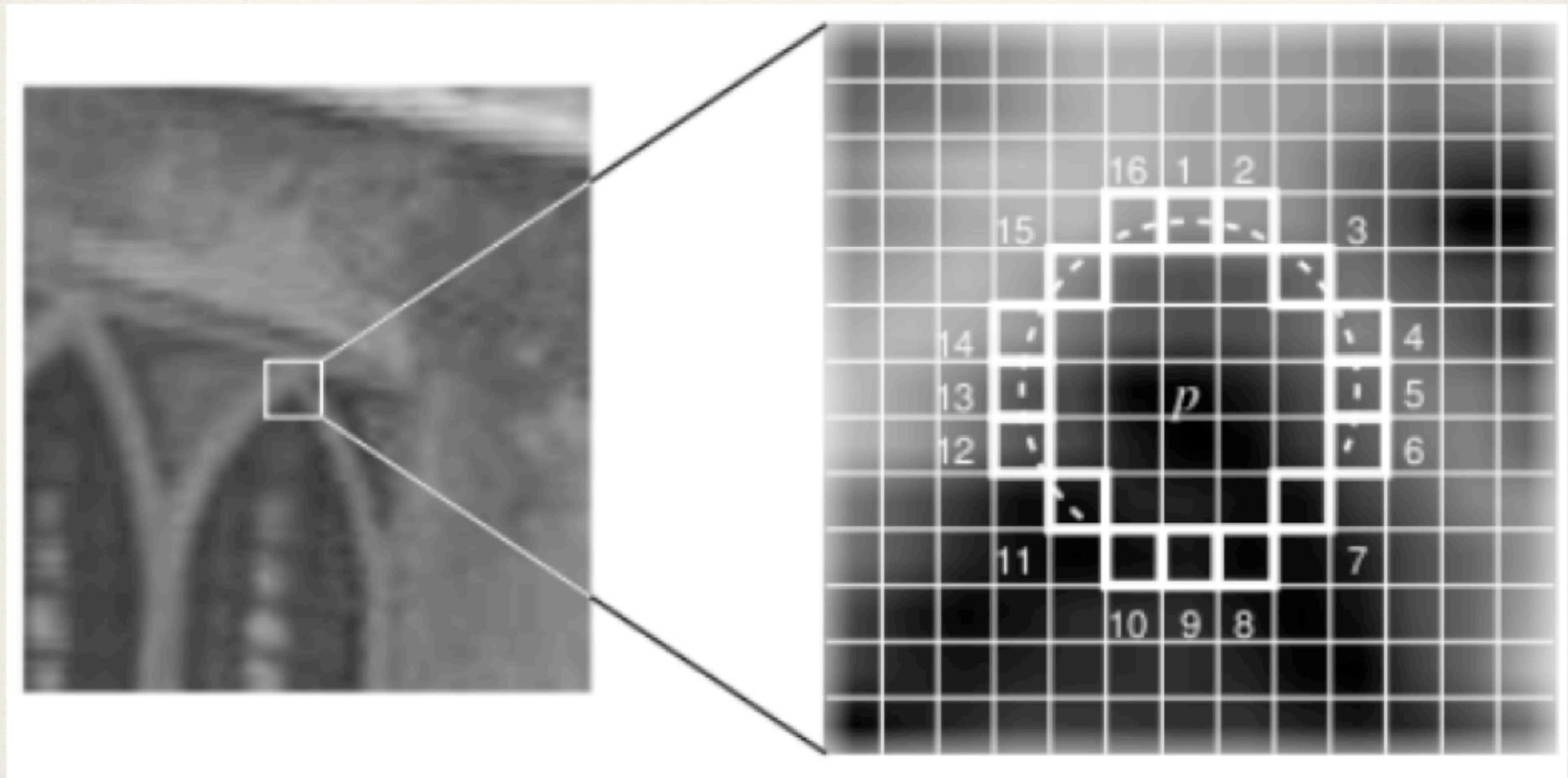
# Generic object recognition

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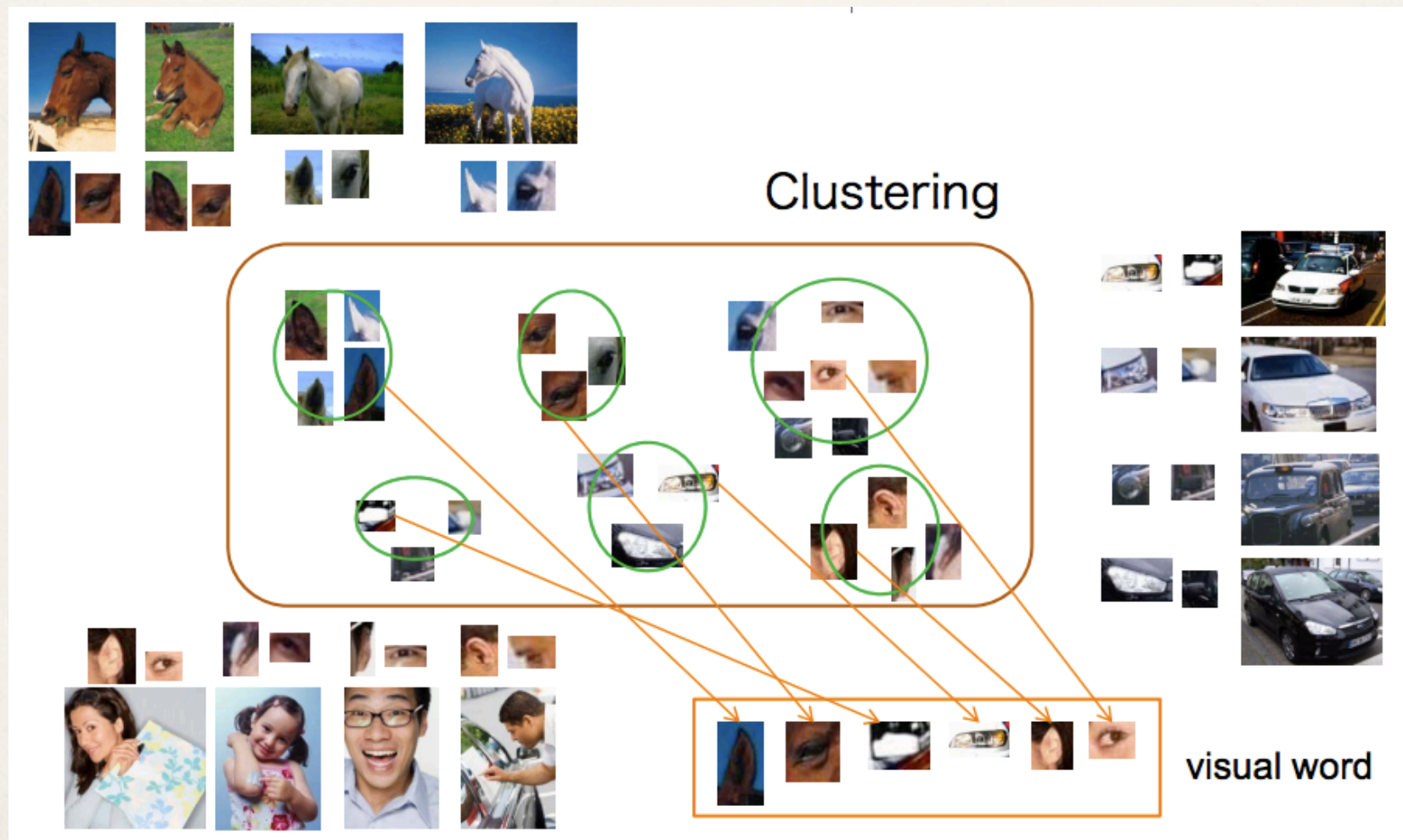


# Feature points and values

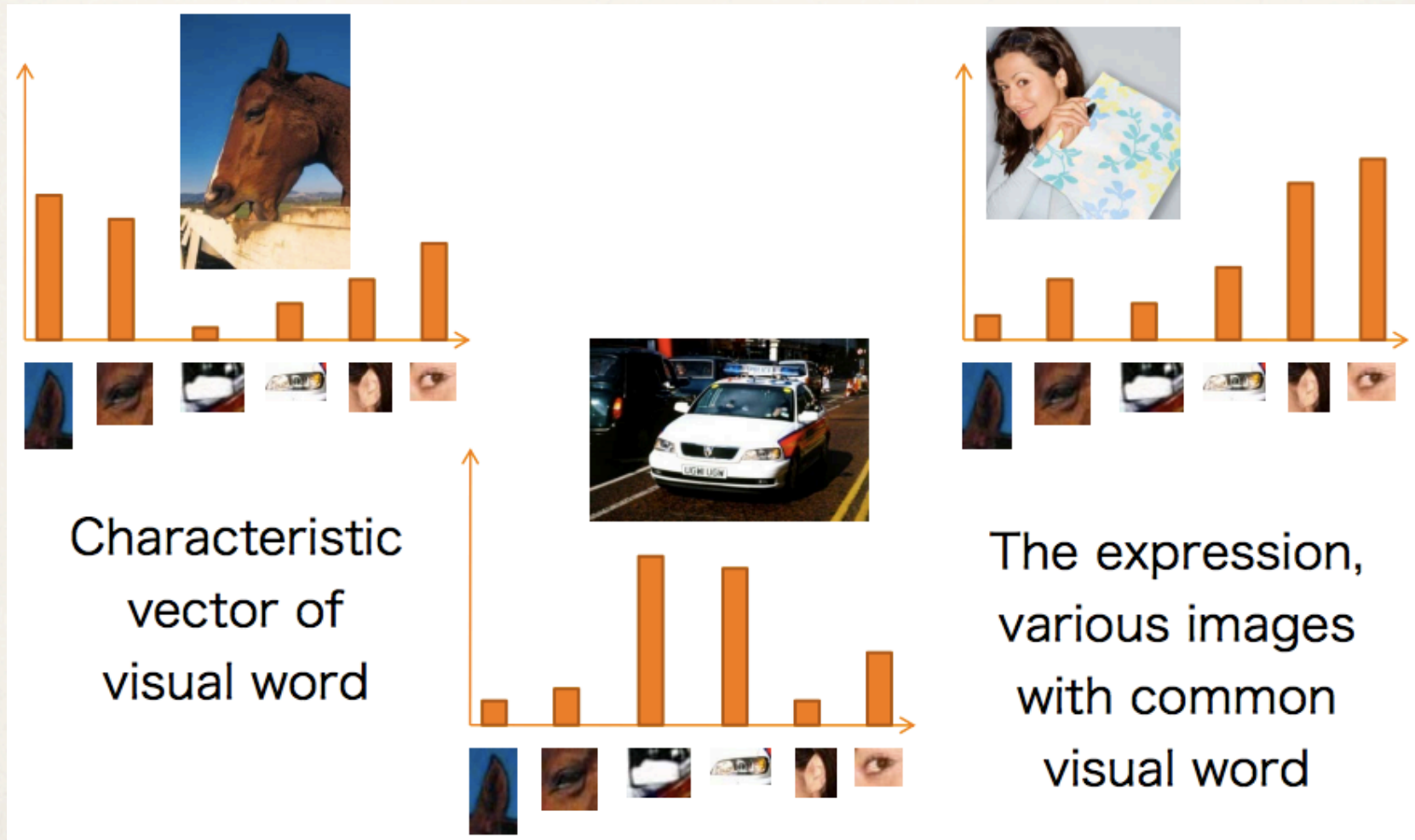
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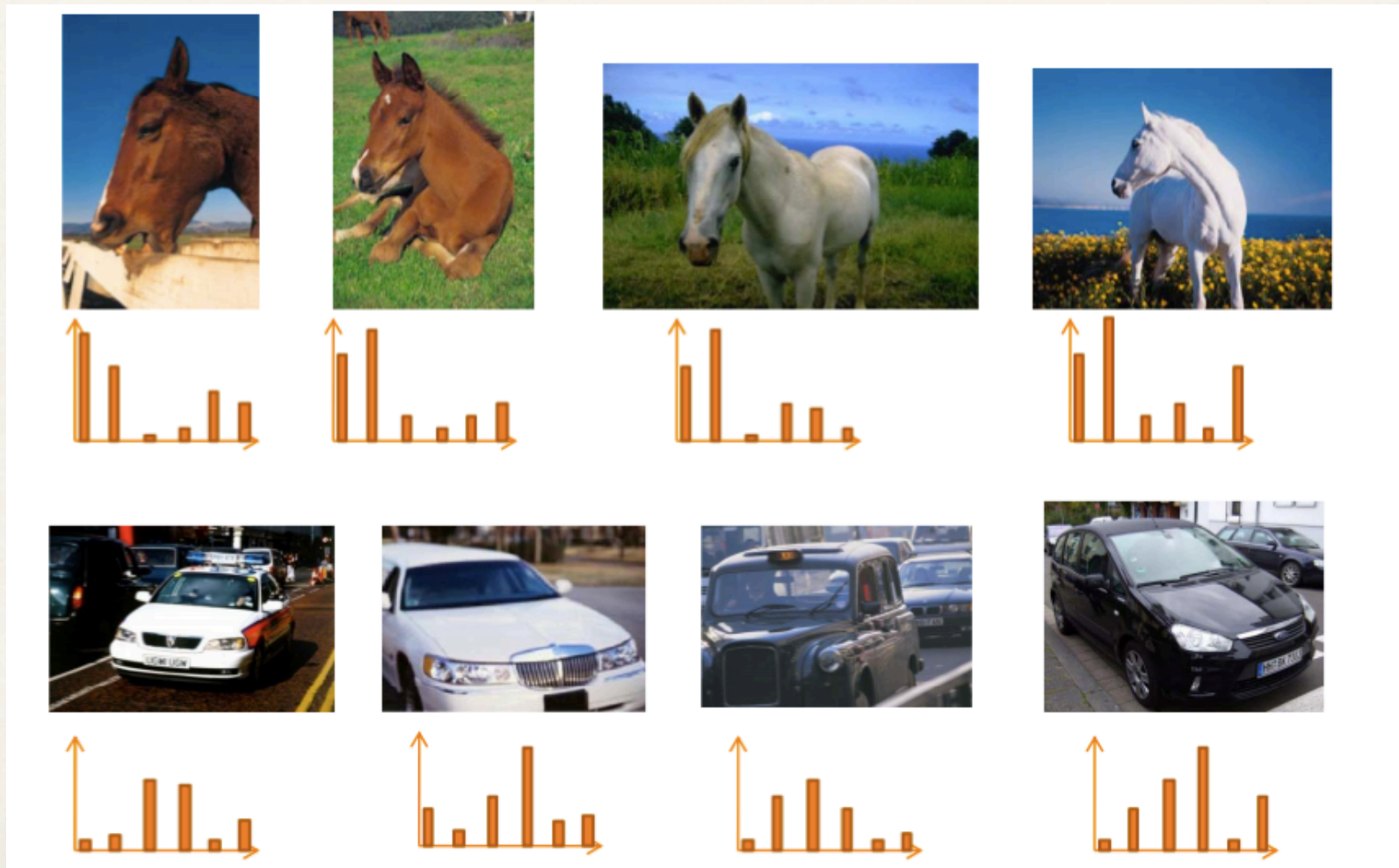
# BOF (Bag of Features)



# BOF (Bag of Features)



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# BOF (Bag of Features)





# Problem

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rotation change



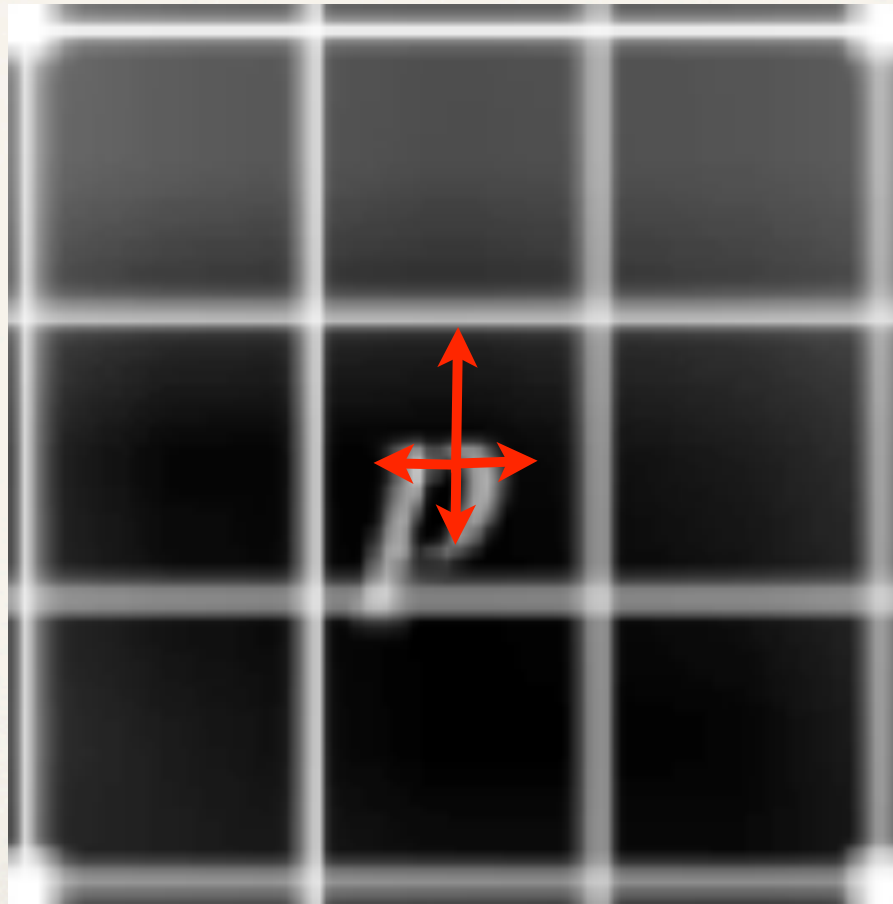
light change



# SIFT (Scale Invariant Feature Transform)

~Direction of luminance~

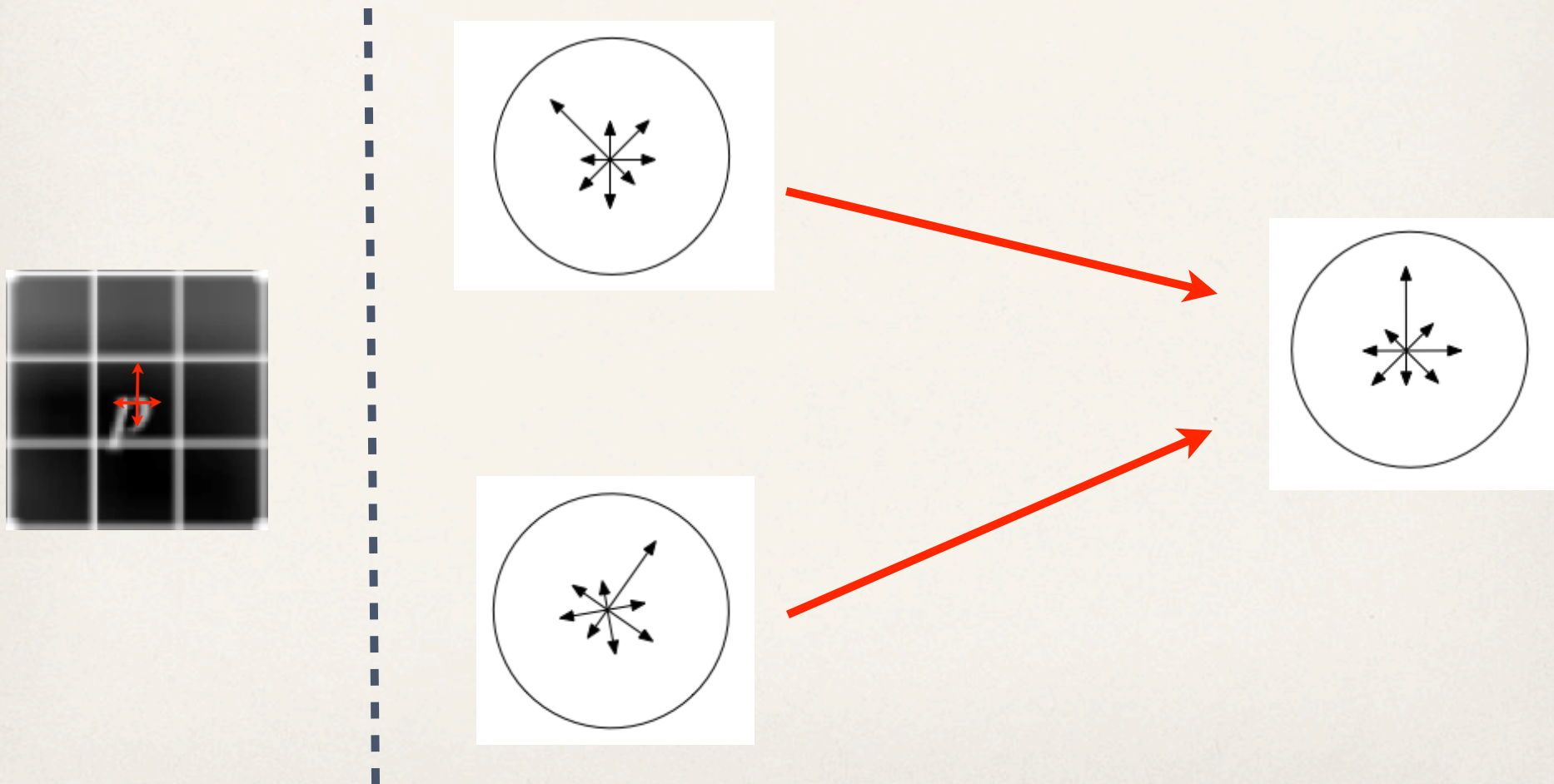
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# SIFT (Scale Invariant Feature Transform)

## ~ Normalize direction ~

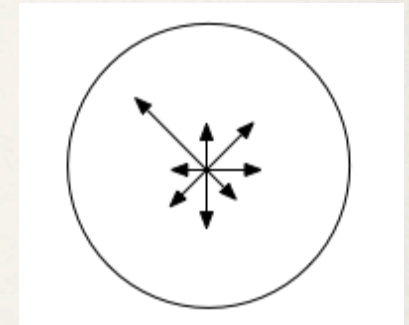
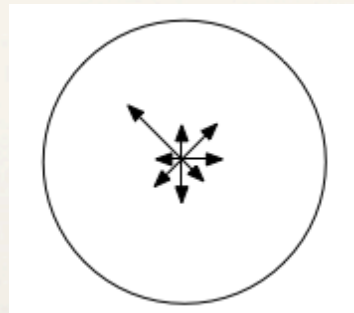
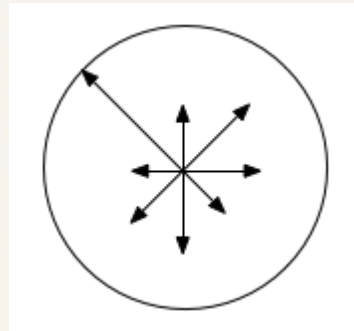
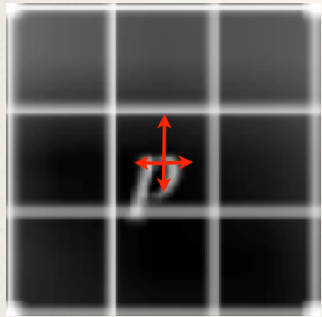
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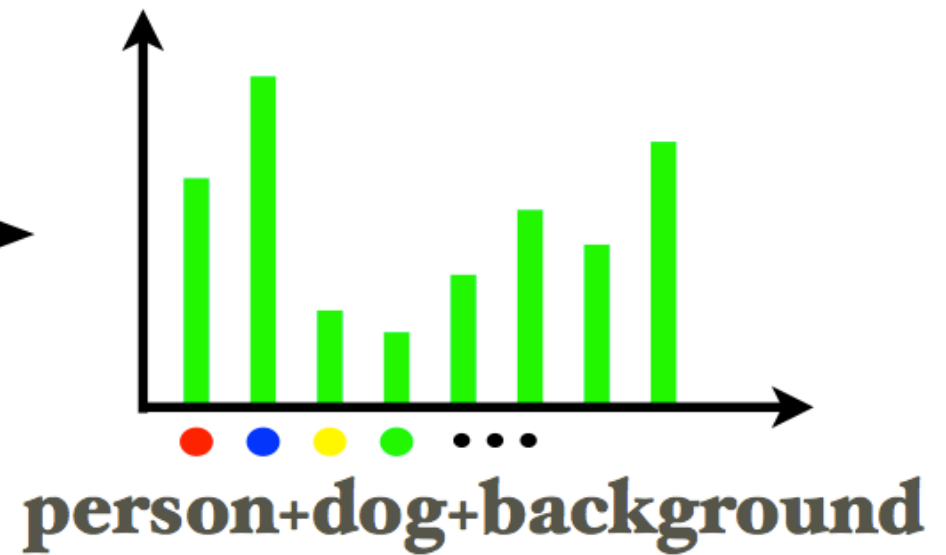
# SIFT (Scale Invariant Feature Transform)

~Normalize feature vector~

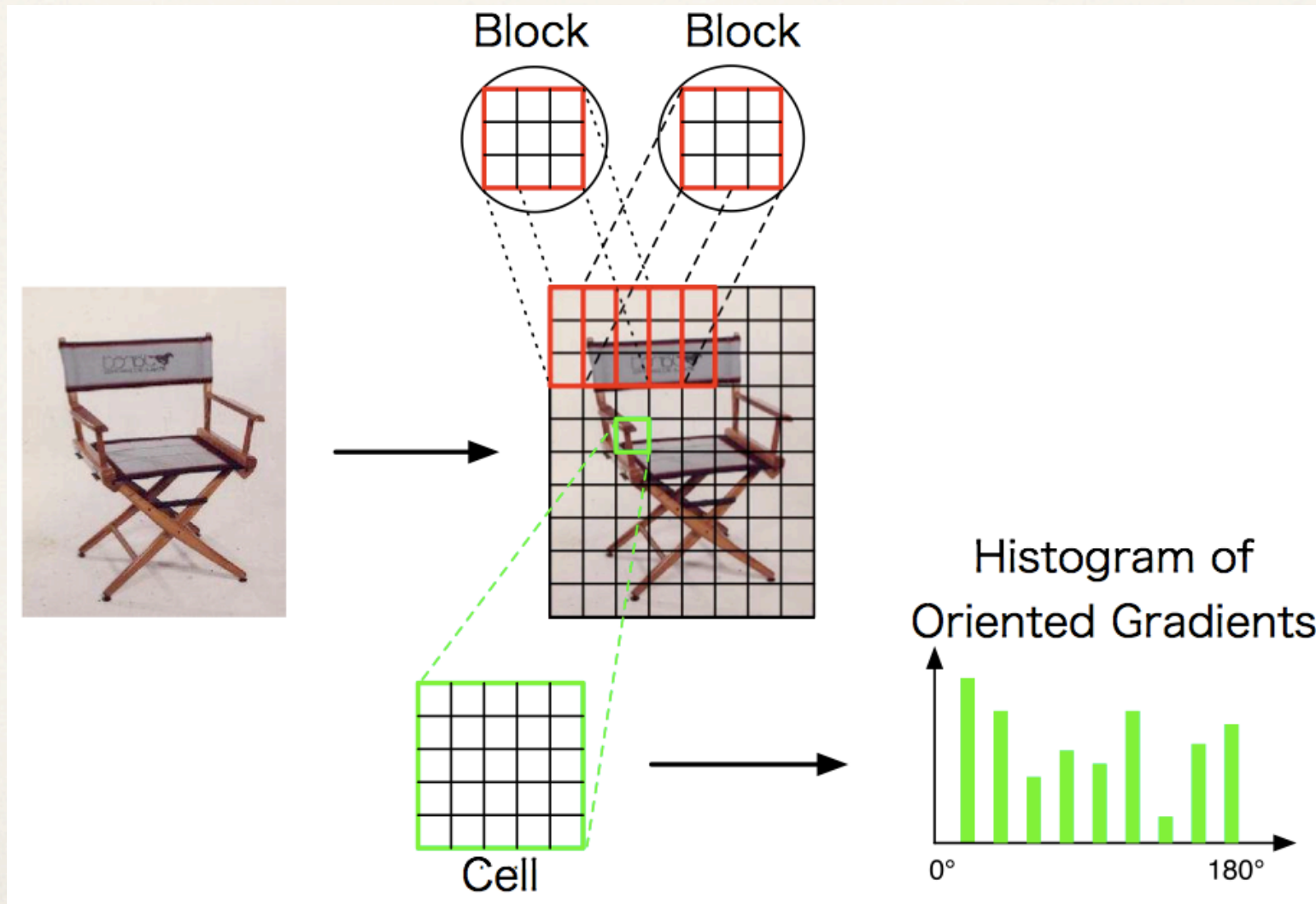
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# Problem of SIFT



# HOG(Histogram of Oriented Gradients)



# Conclusion

~Compare two feature extractor ~

	light change	rotation change	scale change	feature value	use
SIFT	○	○	○	each feature points	specific object recognition and matting
HOG	○	×	×	each images	generic object recognition